

User Manual

QEC-RXXAXXS

EtherCAT Slave ADC/DAC Converter
Up to 8 slots of Analog Input or Output

(Revision 1.1)

REVISION

| DATE | VERSION | DESCRIPTION |
|------------|-------------|---|
| 2024/9/16 | Version 1.0 | New Release. |
| 2024/10/15 | Version 1.1 | Update resolution for Analog Output. Add Index 0x5010 ~ 0x5017 Index's subindex 1: status information. |

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For EtherCAT solution service, support or tutorials, 86Duino Coding IDE 500+ introduction, functions, languages, libraries, etc. Please visit the QEC website:

QEC: https://www.qec.tw/

This Manual is for the OEC series.

SAFETY INFORMATION

- Read these safety instructions carefully.
- Please carry the unit with both hands and handle it with caution.
- Power Input voltage +19 to +50VDC Power Input (Typ. +24VDC)
- Make sure the voltage of the power source is appropriate before connecting the equipment to the power outlet.
- To prevent the QEC device from shock or fire hazards, please keep it dry and away from water and humidity.
- Operating temperature between -20 to +70°C.
- When using external storage as the main operating system storage, ensure the device's power is off before connecting and removing it.
- Never touch un-insulated terminals or wire unless your power adaptor is disconnected.
- Locate your QEC device as close as possible to the socket outline for easy access and avoid force caused by the entangling of your arms with surrounding cables from the QEC device.
- If your QEC device will not be used for a period of time, make sure it is disconnected from the power source to avoid transient overvoltage damage.

WARNING!



DO NOT ATTEMPT TO OPEN OR TO DISASSEMBLE THE CHASSIS (ENCASING) OF THIS PRODUCT. PLEASE CONTACT YOUR DEALER FOR SERVICING FROM OUALIFIED TECHNICIAN.

Content

| Content | ••••• | | iv |
|-----------|-------------|---|----|
| Ch. 1 Ger | neral Infor | mation | 1 |
| 1.1 | Introduc | tion | 2 |
| 1.2 | Specific | ations | 3 |
| | Analo | g Input (QEC-RXXA80S) | 3 |
| | Analo | g Output (QEC-RXXA08S) | 4 |
| | Analo | g Input/Output (QEC-RXXA44S) | 5 |
| 1.3 | Dimensi | on | 6 |
| 1.4 | Mountin | g Instruction | 7 |
| 1.5 | Ordering | g Information | 8 |
| | 1.5.1 | Reference Ordering Part Number: | 8 |
| Ch. 2 Ha | rdware Sy | /stem | 9 |
| 2.1 | General | Technical Data | 10 |
| 2.2 | Connec | tor Summary | 11 |
| | 2.2.1 | EtherCAT Interface | 12 |
| | 2.2.2 | Power Connector | 14 |
| | 2.2.3 | Power and Connection Status LEDs | |
| | 2.2.4 | Analog Status LEDs | 18 |
| | 2.2.5 | Analog I/O Connector | 20 |
| | 2.2.6 | DIN-Rail installation | 24 |
| 2.3 | Wiring t | to the Connector | 25 |
| | 2.3.1 | Connecting the wire to the connector | 25 |
| | 2.3.2 | Removing the wire from the connector | |
| | 2.3.3 | Application Wiring | 26 |
| Ch. 3 Hai | rdware Ins | stallation | 28 |
| 3.1 | DIN-Rail | installation | 29 |
| 3.2 | Removi | ng QEC-RXXA Unit | 30 |
| Ch. 4 Eth | nerCAT Co | ommunication | 31 |
| 4.1 | EtherCA | AT Basics | 32 |
| 4.2 | EtherC/ | AT Cabling | 32 |
| 4.3 | EtherCA | AT State Machine | 33 |
| Ch. 5 Get | tting Start | ted | 35 |
| 5.1 | - | re Preparation and Connection | |
| 5.2 | | re/Development Environment | |
| 5.3 | | t to your PC and set up the environment | |
| 5.4 | | ration and Operation | |

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| | Step 1 | I: Turn on 86EVA and scan | 41 |
|-----------|-----------|----------------------------------|----|
| | Step 2 | 2: Set the parameters | 42 |
| | Step 3 | 3: Generate the code | 45 |
| | Step 4 | 4: Upload the code | 47 |
| 5.5 | Write th | e code | 48 |
| | 5.5.1 | Examples | 49 |
| | 5.5.2 | Access Further Documentation | 52 |
| Ch. 6 Sla | ve Inform | ation | 53 |
| 6.1 | ESI (Ethe | erCAT Slave Information) file | 54 |
| 6.2 | Object D | Dictionary | 54 |
| | 6.2.1 | Standard Objects | 55 |
| | 6.2.2 | Manufacturer Objects | 57 |
| | 6.2.3 | Function Objects | 58 |
| | 6.2.4 | Especial Objects (0x6000-0xFFFF) | 74 |
| Warranty | / | | 79 |

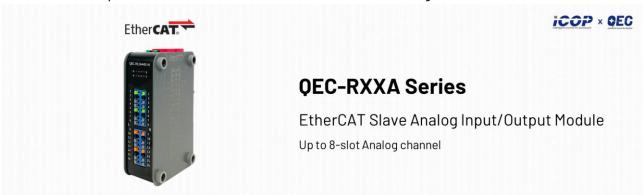
Ch. 1

General Information

- 1.1 Introduction
- 1.2 Specifications
- 1.3 Dimension
- 1.4 Mounting Instruction
- 1.5 Ordering Information

1.1 Introduction

The QEC-RXXA series is an EtherCAT Analog Input/Output Converter. It supports up to 8-slot Analog channels, and customers can customize the Analog Input and Output configuration. This series has passed the verification of conformance testing tools.



The Analog input channels of the QEC-RXXA series offer multiple voltage ranges, both bipolar and unipolar, to accommodate various sensors and transducers. It features a constant resistive input impedance of at least 1 M Ω and is equipped with robust overvoltage protection up to ± 20 V, ensuring durability and stability in harsh industrial settings. The high-resolution 16-bit ADC guarantees precision data acquisition with an accuracy of $\pm 0.2\%$ Full Scale Range (FSR) at 25°C. Conversely, the Analog output channels of the QEC-RXXA series provide flexible signal conditioning capabilities with output current ranging from 0 mA to 24 mA and output voltage settings up to ± 12 V. These outputs are characterized by a 16-bit resolution and an impressive accuracy of $\pm 0.2\%$ FSR at 25°C, suitable for controlling actuators or interfacing with other control systems.

The QEC-RXXA series module supports firmware updates via the File over EtherCAT (FoE) protocol and includes dual RJ-45 ports to facilitate EtherCAT cable redundancy, enhancing network reliability. Diagnostic and operational statuses are easily visible through LED indicators, simplifying troubleshooting and system checks.

The module reduces infrastructure and operational costs by being designed for flexibility in installation and connectivity. It supports various network topologies, such as star, line, or ring, ensuring adaptability to specific project requirements. Measuring $107.45 \times 66 \times 30$ mm, the QEC-RXXA series operates efficiently within a standard temperature range of -20 to +70°C, with options available for extended temperature conditions. The device can be easily mounted using a Din Rail kit that simplifies installation and maintenance.

The QEC-RXXA44S from ICOP is an exemplary solution for industries seeking reliable and precise analog input and output functionality within their EtherCAT networks.

1.2 Specifications

Analog Input (QEC-RXXA80S)

8-slot Analog Input.

| Analog Input | |
|------------------------|---|
| Channels | 8(Differential) |
| Input Type | Voltage (V) |
| Input Range | ±22 V; ±20 V; ±11 V; ±10 V; ±5 V; 0 V – 22V; 0 V – 20 V; 0 V – 11 V; 0 V – 10 V |
| Input Impedance | Constant resistive ≥ 1 MΩ |
| Overvoltage Protection | Up to ±24 V |
| Resolution | 16-bit with accuracy ±0.2% FSR @25°C |
| Sample Rate | Max. 10 kSPS |
| General | |
| Connector | Euroblock Push-in Terminal |
| Connector Color | Analog Input: Green; Negative: Black; Null: Gray; |
| Protocol | EtherCAT (RJ-45 x 2) |
| Ethernet Standard | IEEE 802.3 |
| Transmission Rate | 100Mbps |
| Power Connector | 6-pin Power Input/Output |
| Power Requirement | +19 to +50VDC Power Input (Typ. +24VDC@200mA) |
| Power Consumption | 4.8 W |
| LED Indicator | PWR, RUN, LINK, ERROR, Analog Input/Output status |
| Certifications | CE, FCC, VCCI |
| Environment | |
| Operating Temperature | -20 to +70 °C |
| Storage Temperature | -40~85°C |
| Relative Humidity | 95% (non-condense) |
| Hardware | |
| Dimension | 107.45 x 66 x 30mm (Without DIN-Rail) |
| Weight | 245 g |
| Installation | DIN-Rail Mounting |
| Internal Monitoring | Temperature, Voltage, Current |

Analog Output (QEC-RXXA08S)

8-slot Analog Output.

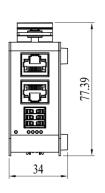
| Analog Output | |
|-----------------------|--|
| Channels | 8 |
| Output Type | Voltage (V, mV), Current (mA) |
| Output Current | 0 mA - 24 mA; 3.5 mA - 23.5 mA; 0 mA - 20 mA; 4 mA - 20 mA; ±24 mA |
| Output Voltage | 0 V - 5 V; 0 V - 10 V; ±5 V; ±10 V; - 0 V - 6 V; 0 V - 12 V; ±6 V; ±12 V |
| Resolution | 16-bit with accuracy ±0.2% FSR@25°C |
| Slew Rate | Configurable (Option) |
| Drift | ±10 ppm/°C |
| General | |
| Connector | Euroblock Push-in Terminal |
| Connector Color | Analog Output: Orange; Negative: Black; Null: Gray; |
| Protocol | EtherCAT (RJ-45 x 2) |
| Ethernet Standard | IEEE 802.3 |
| Transmission Rate | 100Mbps |
| Power Connector | 6-pin Power Input/Output |
| Power Requirement | +19 to +50VDC Power Input (Typ. +24VDC@200mA) |
| Power Consumption | 4.8 W |
| LED Indicator | PWR, RUN, LINK, ERROR, Analog Input/Output status |
| Certifications | CE, FCC, VCCI |
| Environment | |
| Operating Temperature | -20 to +70 °C |
| Storage Temperature | -40~85°C |
| Relative Humidity | 95% (non-condense) |
| Hardware | |
| Dimension | 107.45 x 66 x 30mm (Without DIN-Rail) |
| Weight | 245 g |
| Installation | DIN-Rail Mounting |
| Internal Monitoring | Temperature, Voltage, Current |

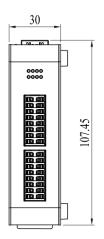
Analog Input/Output (QEC-RXXA44S)

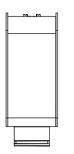
4-slot Analog Input and 4-slot Analog Output.

| Analog Input | | Analog Output | | | | |
|---------------------------|--|--------------------|---|--|--|--|
| Channels | 4 (Differential) | Channels | 4 | | | |
| Input Type | Voltage (V) | Output Type | Voltage (V, mV), Current (mA) | | | |
| | ±22 V; ±20 V; ±11 V; ±10 V; ±5 V; 0 | | 0 mA - 24 mA; 3.5 mA - 23.5 mA; 0 | | | |
| Input Range | V - 22V; 0 V - 20 V; 0 V - 11 V; 0 V - 10 V | Output Current | mA - 20 mA; 4 mA - 20 mA; ±24 mA | | | |
| Input Impedance | Constant resistive $\geq 1 M\Omega$ | Output Voltage | 0 V - 5 V; 0 V - 10 V; ±5 V; ±10 V; - 0 V - 6 V; 0 V - 12 V; ±6 V; ±12 V | | | |
| Overvoltage Protection | Up to ±24 V | Resolution | 16-bit with accuracy ±0.2% FSR@25°C | | | |
| Resolution | 16-bit with accuracy ±0.2% FSR @25°C | Slew Rate | Configurable (Option) | | | |
| Sample Rate | Max. 10 kSPS | Drift | ±10 ppm/°C | | | |
| General | General | | | | | |
| Connector | Euroblock Push-in Terminal | | | | | |
| Connector Color | Analog Input: Green; Analog Outpu | ut: Orange; Negati | ive: Black; Null: Gray; | | | |
| Protocol | EtherCAT (RJ-45 x 2) | | | | | |
| Ethernet Standard | IEEE 802.3 | | | | | |
| Transmission Rate | 100Mbps | | | | | |
| Power Connector | 6-pin Power Input/Output | | | | | |
| Power Requirement | +19 to +50VDC Power Input (Typ. + | 24VDC@200mA) | | | | |
| Power Consumption | 4.8 W | | | | | |
| LED Indicator | PWR, RUN, LINK, ERROR, Analog I | nput/Output statu | JS | | | |
| Certifications | CE, FCC, VCCI | | | | | |
| Environment | | | | | | |
| Operating | 20 + 70 ° 0 | | | | | |
| Temperature | -20 to +70 °C | | | | | |
| Storage Temperature | -40~85°C | | | | | |
| Relative Humidity | 95% (non-condense) | | | | | |
| Hardware | | | | | | |
| Dimension | 107.45 x 66 x 30mm (Without DIN-Rail) | | | | | |
| Weight | 245 g | | | | | |
| | DIN-Rail Mounting | | | | | |
| Installation | DIN-Rail Mounting | | | | | |

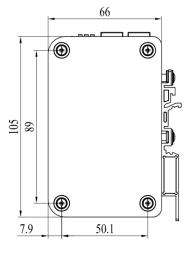
1.3 Dimension

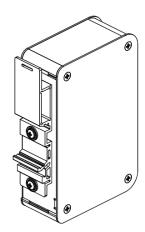


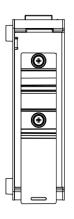












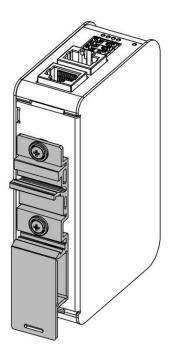
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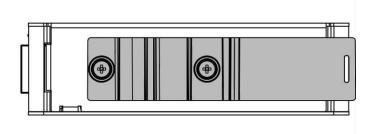
(Unit: mm)

1.4 Mounting Instruction

QEC-RXXA series is an easy-install design to help you set-up your modules easily. Please refer to Ch.3.1 DIN-Rail installation.

DIN-Rill





1.5 Ordering Information

| Type | RJ45 power source | | Functions | | Feature | | Coating | |
|---------|-------------------|--------|-----------|----------|----------|-------------|---------|---|
| .) [- | Input | Output | Analog | Input | Output | Analog Type | _ | |
| QEC-R | X | X | А | <u>X</u> | <u>X</u> | X | | X |

1. Type: Code 1~4

R: EtherCAT Slave.

2. RJ45 Power source: Code 5~6

①: RJ45 In/Out w/o power

1: RJ45 PoE Device, Red Plastic Housing

3. Functions: Code 7~9

A: Analog I/O

X: 0,4,8 input channels

X: 0,4,8 output channels

4. Feature: Code 10

S: Standard

5. Coating: Code 11

C: Yes / N: Normal

1.5.1 Reference Ordering Part Number:

Above is the standard Part Number, please contact our sales if you need to order other part number.

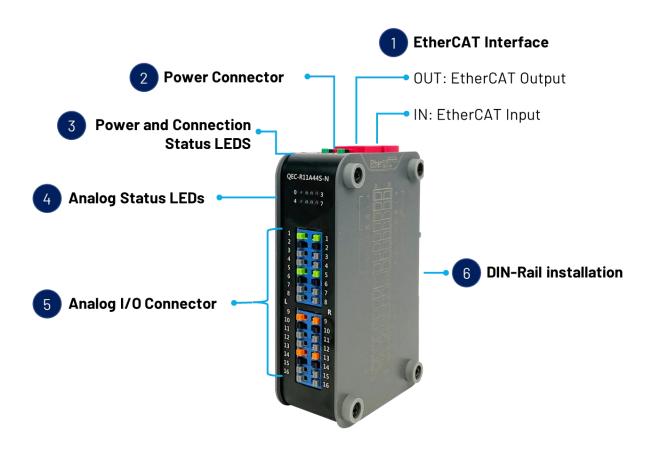
- **QEC-ROOA44S-N:** EtherCAT Slave 4-ch Analog Input and 4-ch Analog Output Module.
- **QEC-R11A80S-N:** EtherCAT Slave 8-ch Analog Input Module/PoE.
- **QEC-R11A08S-C:** EtherCAT Slave 8-ch Analog Output Module/PoE.

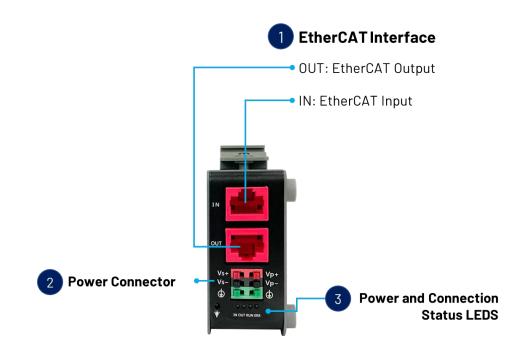
Ch. 2

Hardware System

- 2.1 General Technical Data
- 2.2 Connector Summary
- 2.3 Wiring to the Connector

2.1 General Technical Data



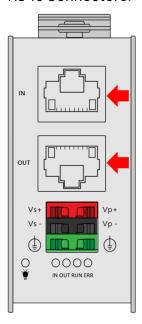


2.2 Connector Summary

| No. | Description | | Type Narrative | Num # |
|-----|----------------------------------|-----|------------------------------|--------|
| 1 | EtherCAT Interface | OUT | RJ45 Connector | 8-pin |
| | EtherCAT interface | IN | (Gold finger) | 8-pin |
| 2 | Power Connector | | Power Socket | 6-pin |
| 3 | Power and Connection Status LEDs | | Status LEDs | - |
| 4 | Analog Status LEDs | | Status LEDs | - |
| 5 | Analog I/O Connector | | Push-in Terminal (Euroblock) | 8-slot |
| 6 | DIN-Rail | | - | - |

2.2.1 EtherCAT Interface

RJ45 Connectors.



ECIN

| | Pin# | Signal Name | Pin# | Signal Name |
|-------|------|-------------|------|-------------|
| 8 2,1 | 1 | LAN1_TX+ | 2 | LAN1_TX- |
| | 3 | LAN1_RX+ | 4 | VS+ |
| | 5 | VP+ | 6 | LAN1_RX- |
| | 7 | VS-(GND) | 8 | VP-(GND) |

^{*} PoE LAN with the Red Housing; Regular LAN with Black Housing.

EC OUT

| 1,2 8 | Pin# | Signal Name | Pin# | Signal Name |
|-------|------|-------------|------|-------------|
| | 1 | LAN2_TX+ | 2 | LAN2_TX- |
| | 3 | LAN2_RX+ | 4 | VS+ |
| | 5 | VP+ | 6 | LAN2_RX- |
| | 7 | VS-(GND) | 8 | VP-(GND) |

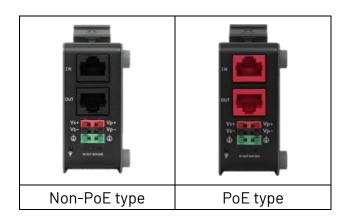
^{*} PoE LAN with the Red Housing; Regular LAN with Black Housing.

^{*} L4, L5, L7, L8 pins are option, for RJ45 Power IN/OUT.

^{*} L4, L5, L7, L8 pins are option, for RJ45 Power IN/OUT.

Note. QEC's PoE (Power over Ethernet)

In QEC product installations, users can easily distinguish between PoE and non-PoE: if the RJ45 house is red, it is PoE type, and if the RJ45 house is black, it is non-PoE type.



PoE (Power over Ethernet) is a function that delivers power over the network. QEC can be equipped with an optional PoE function to reduce cabling. In practice, PoE is selected based on system equipment, so please pay attention to the following points while evaluating and testing:

1. When connecting PoE and non-PoE devices, make sure to disconnect Ethernet cables at pins 4, 5, 7, and 8 (e.g., when a PoE-supported QEC EtherCAT master connects with a third-party EtherCAT slave).



2. The PoE function of QEC is different and incompatible with EtherCAT P, and the PoE function of QEC is based on PoE Type B, and the pin functions are as follows:

| | Pin# | Signal Name | Pin# | Signal Name |
|-------|------|-------------|------|-------------|
| | 1 | LAN1_TX+ | 2 | LAN1_TX- |
| 8 2,1 | 3 | LAN1_RX+ | 4 | VS+ |
| | 5 | VP+ | 6 | LAN1_RX- |
| | 7 | VS-(GND) | 8 | VP-(GND) |

^{*} PoE LAN with the Red Housing; Regular LAN with Black Housing.

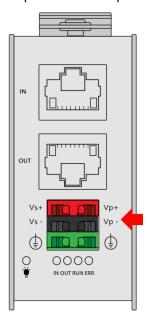
3. QEC's PoE power supply is up to 24V/3A.

^{*}L4, L5, L7, L8 pins are option, for RJ45 Power IN/OUT.

2.2.2 Power Connector

Euroblock Connectors.

4-pins Power Input/Output & 2-pins FGND.



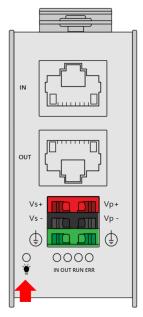
Vs for system power; Vp for peripheral power and backup power.

| Vs+ Vp+ Vp- | Pin# | Signal Name | Pin# | Signal Name |
|-------------|------|-------------|------|-------------|
| | 1 | Vs+ | 2 | Vp+ |
| | 3 | Vs-(GND) | 4 | Vp-(GND) |
| | 5 | F.G | 6 | F.G |

^{*} Power Input voltage +19 to +50VDC Power Input (Typ. +24VDC)

2.2.3 Power and Connection Status LEDs

Power Status LED



Power input is 24V (typical). The LED status provide high/low voltage warning.

| Notation | States | Condition | Description |
|----------|----------------------------|--|--|
| | Green LED On | Voltage <= 50V and >= 45V Voltage <= 26V and >= 19V | When Vs and Vp voltages are confirmed to be normal, the Green LED will remain steady on. |
| PWR 🍎 | Green LED On Red LED On | Voltage < 45V and > 26V Voltage < 19V and > 12V | LEDs will alternately flash (at 0.3-second intervals) until the Vs and Vp voltages are correct. |
| | Orange LED On | Voltage > 50V or < 12V | Orange LED (Green + Red) will continuously flash (at 0.3-second intervals) until the Vs and Vp voltages are correct. |

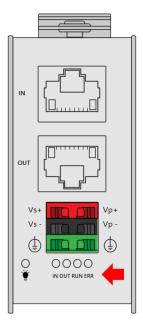
^{*} Vs power status will be displayed first.

Power ERROR Code table (Red LED Flashing Display (2 seconds/cycle)):

| Long Light | Short Flash Description | | |
|---------------|--|--|--|
| | After microchip completes the | BootLoad test, it proceeds to the APP program stage. | |
| Olonglight | 1 short flash | microchip communication with the EtherCAT chip failed. | |
| 0 Long Light | 2 short flashes | EtherCAT chip internal RAM test failed. | |
| | 5 short flashes | Quartz oscillator on the board abnormality. | |
| | Indicates the microchip BootLoad stage during startup, APP program not yet executed. | | |
| 1 Long Light | 1 short flash | microchip internal SRAM failed. | |
| | 2 short flashes | APP software CHECKSUM failed. | |
| 2 Long Lights | Not yet defined. | | |

^{*} Note: If you encounter any of the above abnormal states, please contact us.

Connection Status LEDs



EtherCAT: PWR, RUN, LINK, and ERROR Status LEDs

| Notation | Color | States | Description |
|----------|-------|--------------|---------------------------------------|
| | | Off | No link |
| In | Green | Blinking | Link and activity |
| | | On | Link without activity |
| | | Off | No link |
| Out | Green | Blinking | Link and activity |
| | | On | Link without activity |
| | | Off | The device is in state INIT |
| Dun | Croon | Blinking | The device is in state Pre-Operation |
| Run | Green | Single Flash | The device is in state Safe-Operation |
| | | On | The device is in state Operation |
| | | Off | No error |
| | | Blinking | Invalid Configuration |
| Err | Red | Single Flash | Local Error |
| | Reu | Double Flash | Process Data Watchdog Timeout |
| | | Double Flash | EtherCAT Watchdog Timeout |
| | | On | The device is in state Error |

2.2.4 Analog Status LEDs

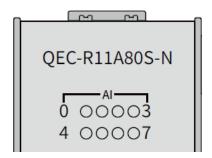
The QEC series modules are equipped with status LEDs that serve as indicators of the operational state of the internal chips rather than the status of the analog input or output channels. These LEDs remain bright to signify that the internal components are functioning correctly.

LED Behavior:

- Always Bright: The internal chips are functioning normally.
- Off: Indicates that the internal chip for the corresponding channel is not operational, which may suggest a fault or failure.

Analog Input (QEC-RXXA80S)

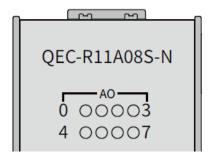
8-slot Analog Input.



The module features 8 status LEDs corresponding to its 8 analog input channels. These LEDs are always bright when the internal chips controlling each input channel are operational.

Analog Output (QEC-RXXA08S)

8-slot Analog Output.

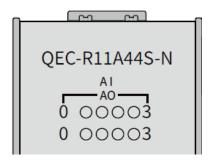


This module has 8 status LEDs for its 8 analog output channels.

Each LED remains bright to indicate the internal chip for the corresponding output channel is functioning.

Analog Input/Output (QEC-RXXA44S)

4-slot Analog Input and 4-slot Analog Output.



This combination module has 4 status LEDs for the analog inputs (upper side) and 4 status LEDs for the analog outputs (lower side).

The LEDs will be continuously bright, confirming that the internal chips for both the input and output channels are working properly.

2.2.5 Analog I/O Connector

For EtherCAT Slave index assignments, refer to <u>6.2.3 Function Objects</u>.

Analog Input (QEC-RXXA80S)

The QEC-RXXA80S module supports 8 differential analog input channels (Al00 to Al07).

Analog Input: Positive (Green), Negative (Black).

Others: NC (Gray).

| Pin# | Signal Name | AI — | Pin# | Signal Name |
|------|-------------|----------------------------|------|-------------|
| 1+ | AI01+ | 1+ 10010+ | 0+ | AI00+ |
| 1- | AI01- | 1- 0- | 0- | AI00- |
| - | NC | NC NC NC | - | NC |
| - | NC | NC NC NC | - | NC |
| 3+ | AI03+ | 3+ TQ DT 2+ 3- TQ DT 2- | 2+ | AI02+ |
| 3- | A103- | NC TO OTT NC | 2- | AI02- |
| - | NC | NC TO DIT NC | - | NC |
| - | NC | | - | NC |
| 5+ | AI05+ | 5+ 110 011 4+ | 4+ | AI04+ |
| 5- | AI05- | 5- | 4- | AI04- |
| - | NC | NC TO OT NC | - | NC |
| - | NC | 7+ 110 011 6+ | - | NC |
| 7+ | AI07+ | 7- 6- | 6+ | AI06+ |
| 7- | AI07- | NC TO STINC | 6- | AI06- |
| _ | NC | NC NC NC | _ | NC |
| _ | NC | | _ | NC |

Analog Input Specifications:

- Input Type: Voltage (V)
- Input Range ±22 V; ±20 V; ±11 V; ±10 V; ±5 V; 0 V 22V; 0 V 20 V; 0 V 11 V; 0 V 10 V
- Input Impedance: Constant resistive $\geq 1 M\Omega$
- Overvoltage Protection: Up to ±24 V
- Resolution: 16-bit with accuracy of ±0.2% Full-Scale Range (FSR) at 25°C

Analog Output (QEC-RXXA08S)

The QEC-RXXA08S module supports 8 analog output channels (A000 to A007).

Analog Output: Positive (Orange), Negative (Black).

Others: NC (Gray).

| Pin# | Signal Name | 11 40 11 | Pin# | Signal Name |
|------|-------------|-----------------------------|------|-------------|
| 1+ | A001+ | 1+ 10 0+ | 0+ | A000+ |
| 1- | A001- | 1- 0- 0- | 0- | A000- |
| - | NC | NC MC NC | - | NC |
| - | NC | NC MC NC | _ | NC |
| 3+ | A003+ | 3+ TQ DT 2+ 3- TQ DT 2- | 2+ | A002+ |
| 3- | A003- | NC TO OT NC | 2- | A002- |
| - | NC | NC NC NC | - | NC |
| - | NC | | - | NC |
| 5+ | A005+ | 5+ 10 01 4+ | 4+ | A004+ |
| 5- | A005- | 5- 10 01 4- NC 110 01 NC | 4- | A004- |
| - | NC | NC MC NC | - | NC |
| - | NC | 7+ 6+ | - | NC |
| 7+ | A007+ | 7- 6- | 6+ | A006+ |
| 7- | A007- | NC TO STINC | 6- | A006- |
| - | NC | NC NC | - | NC |
| _ | NC | | _ | NC |

Analog Output Specifications:

- Output Type: Voltage (V, mV), Current (mA)
- Output Current: 0 mA 24 mA; 3.5 mA 23.5 mA; 0 mA 20 mA; 4 mA 20 mA; ±24 mA
- Output Voltage: 0 V 5 V; 0 V 10 V; ±5 V; ±10 V; 0 V 6 V; 0 V 12 V; ±6 V; ±12 V
- Resolution: 16-bit with accuracy ±0.2% FSR@25°C
- Slew Rate: Configurable (Option)
- Drift: ±10 ppm/°C

Analog Input/Output (QEC-RXXA44S)

The QEC-RXXA44S module supports 4 differential analog input channels (Al00 to Al03) and 4 analog output channels (A000 to A003).

Analog Input: Positive (Green), Negative (Black).
Analog Output: Positive (Orange), Negative (Black).

Others: NC (Gray).

| Pin# | Signal Name | II — AI — II | Pin# | Signal Name |
|------|-------------|--|------|-------------|
| 1+ | AI01+ | 1+ 100100+ | 0+ | AI00+ |
| 1- | AI01- | 1- 0- 0- | 0- | AI00- |
| - | NC | NC MC NC | - | NC |
| - | NC | NC NC NC | - | NC |
| 3+ | AI03+ | 3+ <u> </u> | 2+ | AI02+ |
| 3- | AI03- | NC TO OT NC | 2- | AI02- |
| - | NC | NC NC NC | - | NC |
| - | NC | AO | - | NC |
| 1+ | A001+ | 1+ 10 0+ | 0+ | A000+ |
| 1- | A001- | 1- 0- 0- NC NC | 0- | A000- |
| - | NC | NC TO OTT NC | - | NC |
| - | NC | 3+ 11 2+ | - | NC |
| 3+ | A003+ | 3- 2- | 2+ | A002+ |
| 3- | A003- | NC NC | 2- | A002- |
| - | NC | NC NC NC | - | NC |
| - | NC | | - | NC |

Analog Input Specifications:

- Input Type: Voltage (V)
- Input Range ±22 V; ±20 V; ±11 V; ±10 V; ±5 V; 0 V 22V; 0 V 20 V; 0 V 11 V; 0 V 10 V
- Input Impedance: Constant resistive $\geq 1 M\Omega$
- Overvoltage Protection: Up to ±24 V
- Resolution: 16-bit with accuracy of ±0.2% Full-Scale Range (FSR) at 25°C

Analog Output Specifications:

- Output Type: Voltage (V, mV), Current (mA)
- Output Current: 0 mA 24 mA; 3.5 mA 23.5 mA; 0 mA 20 mA; 4 mA 20 mA; ±24 mA
- Output Voltage: 0 V 5 V; 0 V 10 V; ±5 V; ±10 V; 0 V 6 V; 0 V 12 V; ±6 V; ±12 V

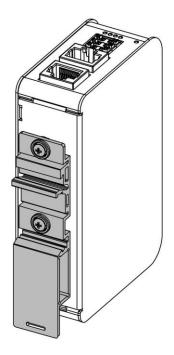
• Resolution: 16-bit with accuracy ±0.2% FSR@25°C

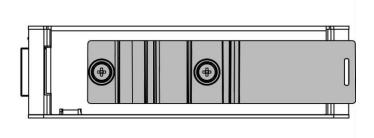
• Slew Rate: Configurable (Option)

• Drift: ±10 ppm/°C

2.2.6 DIN-Rail installation

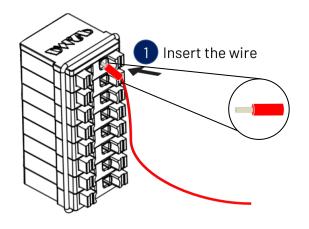
Please refer to Ch.3.1 DIN-Rail installation.

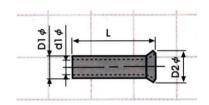




2.3 Wiring to the Connector

2.3.1 Connecting the wire to the connector

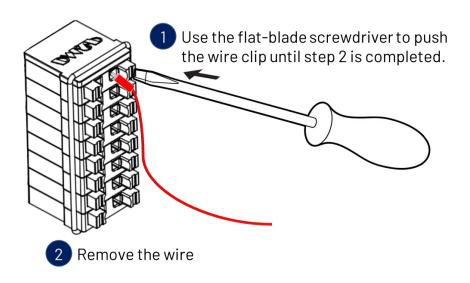




Insulated Terminals Dimensions (mm)

| Position | L | ØD1 | Ød1 | ØD2 |
|-----------|------|-----|-----|-----|
| CN 0.5-6 | 6.0 | 1.3 | 1.0 | 1.9 |
| CN 0.5-8 | 8.0 | 1.3 | 1.0 | 1.9 |
| CN 0.5-10 | 10.0 | 1.3 | 1.0 | 1.9 |

2.3.2 Removing the wire from the connector



2.3.3 Application Wiring

Analog Input

Example for Analog Input Operation. (QEC-RXXA80S/QEC-RXXA44S)

In the following diagram, an analog input operation is shown using Channel 0 (AlOO) of the QEC-RXXA module. The positive terminal (AlOO+) connects to the signal source, and the negative terminal (AlOO-) connects to the ground (GND).

- AlOO+: Connects to the positive side of the input signal (e.g., a voltage sensor).
- AlOO-: Connects to the negative side (ground) of the input signal.

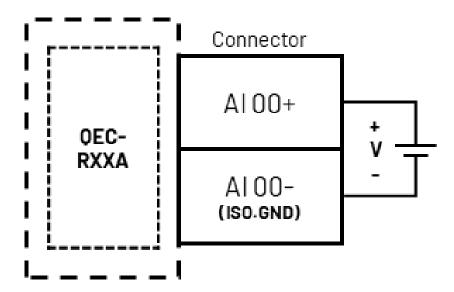


Figure 1: Analog Input Wiring Example

* Important Note: Ensure the input voltage does not exceed the specified range to avoid damaging the device.

Analog Input Specification:

| Input Type | Voltage (V) |
|------------------------|---|
| Input Range | ±22 V; ±20 V; ±11 V; ±10 V; ±5 V; 0 V – 22V; 0 V – 20 V; 0 V – 11 V; 0 V – 10 V |
| Input Impedance | Constant resistive $\geq 1 M\Omega$ |
| Overvoltage Protection | Up to ±24 V |

Analog Output

Example for Analog Output Operation. (QEC-RXXA08S/QEC-RXXA44S)

The diagram below illustrates an example of analog output wiring using Channel 0 (A000) of the QEC-RXXA module. This channel can output either a voltage or current signal, depending on the connected device.

Current:

- A000+: Connects to the positive side of the device receiving the signal.
- A000-: Connects to the ground of the device receiving the signal.

Voltage:

- A001+: Connects to the positive side of the device receiving the signal.
- A001-: Connects to the ground of the device receiving the signal.

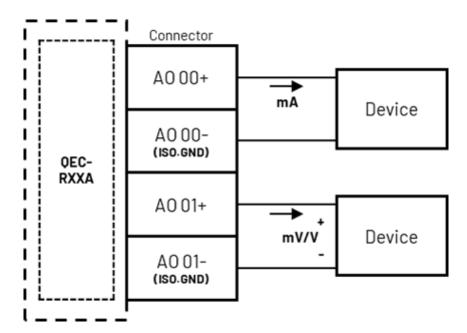


Figure 2: Analog Output Wiring Example

* Important Note: Ensure the connected device supports the output type (voltage or current) to avoid misconfiguration.

Analog Output Specification:

| Output Type | Voltage (V, mV), Current (mA) |
|----------------|--|
| Output Current | 0 mA - 24 mA; 3.5 mA - 23.5 mA; 0 mA - 20 mA; 4 mA - 20 mA; ±24 mA |
| Output Voltage | 0 V - 5 V; 0 V - 10 V; ±5 V; ±10 V; - 0 V - 6 V; 0 V - 12 V; ±6 V; ±12 V |

Ch. **3**

Hardware Installation

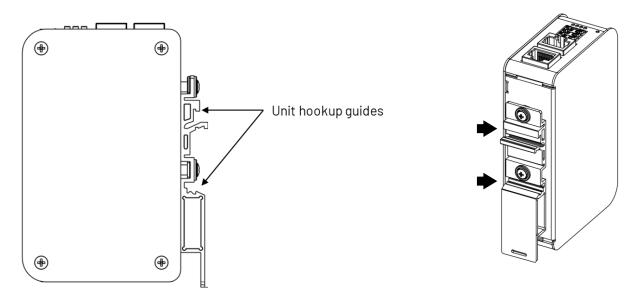
3.1 DIN-Rail installation

3.2 Removing QEC-RXXA Unit

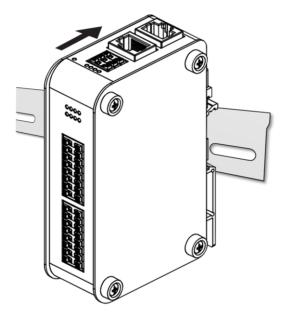
This section describes how to install QEC-RXXA. Please turn OFF the power supply before you mount QEC-RXXA. Always mount QEC-RXXA one at a time.

3.1 DIN-Rail installation

Slide in the QEC-RXXA on the hookup guides and press the QEC-RXXA with a certain amount of force against the DIN track until the DIN Track mounting hook lock into place.



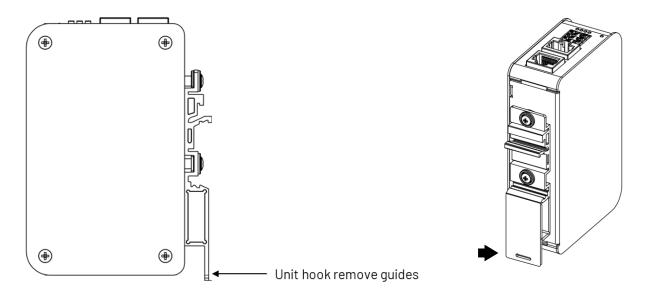
When you mount the QEC-RXXA, releasing the DIN track mounting hook on the QEC-RXXA is unnecessary. After you mount the QEC-RXXA, make sure it is locked to the DIN Track.



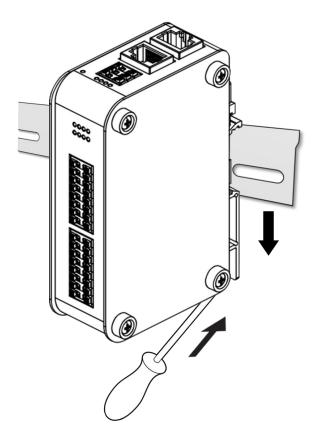
Note: Always turn OFF the Unit power supply and I/O power supply before connecting and removing the QEC-RXXA.

3.2 Removing QEC-RXXA Unit

Use a flat-blade screwdriver to remove the DIN Track mounting hook on the unit.



Pull down and out the flat-blade screwdriver with force against the DIN track until you hear the DIN Track remove the hook.



Ch. 4

EtherCAT Communication

- 4.1 EtherCAT Basics
- 4.2 EtherCAT Cabling
- 4.3 EtherCAT State Machine

4.1 EtherCAT Basics

EtherCAT (Ethernet for Control Automation Technology) is an Ethernet-based fieldbus system developed by Beckhoff Automation. The protocol is standardized in IEC 61158 and is suitable for both hard and soft real-time computing requirements in automation technology.

The goal during the development of EtherCAT was to apply Ethernet for automation applications requiring short data update times (also called cycle times; \leq 100 µs) with low communication jitter (for precise synchronization purposes; \leq 1 µs) and reduced hardware costs. Typical application fields for EtherCAT are machine controls (e.g., semiconductor tools, metal forming, packaging, injection molding, assembly systems, printing machines, robotics). Remote-controlled hump yard facilities are used in the railroad industry.

4.2 EtherCAT Cabling

The cable length between two EtherCAT devices must not exceed 100 m.

Cables and connectors

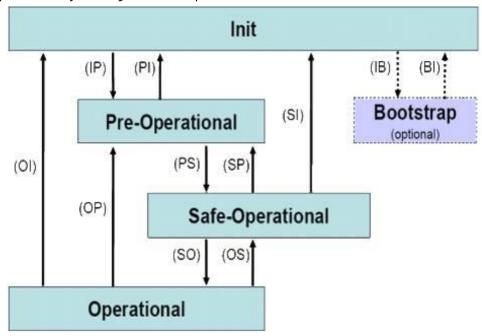
For connecting EtherCAT devices, only Ethernet connections (cables + plugs) that meet the requirements of at least category 5 (CAT5) according to EN 50173 or ISO/IEC 11801 should be used. EtherCAT uses 4 wires for signal transfer.

The pin assignment is compatible with the Ethernet standard (ISO/IEC 8802-3).

| Pin | Color of conductor | Signal | Description |
|-----|--------------------|--------|--------------------|
| 1 | Yellow | TD+ | Transmission Data+ |
| 2 | Orange | TD- | Transmission Data- |
| 3 | White | RD+ | Receiver Data+ |
| 6 | Blue | RD- | Receiver Data- |

4.3 EtherCAT State Machine

The state of the EtherCAT slave is controlled via the EtherCAT State Machine (ESM). Depending upon the state, different functions are accessible or executable in the EtherCAT slave. Specific commands must be sent by the EtherCAT master to the device in each state, particularly during the bootup of the slave.



A distinction is made between the following states:

- Init
- Pre-Operational
- Safe-Operational and
- Operational
- Boot

The regular state of each EtherCAT slave after bootup is the OP state.

Init

After switch-on the EtherCAT slave in the Init state. No mailbox or process data communication is possible. The EtherCAT master initializes sync manager channels 0 and 1 for mailbox communication.

Pre-Operational (Pre-Op)

During the transition between Init and Pre-Op the EtherCAT slave checks whether the mailbox was initialized correctly. In Pre-Op state mailbox communication is possible, but not process data communication. The EtherCAT master initializes the sync manager channels for process data (from sync manager channel 2), the FMMU channels and, if the slave supports configurable mapping, PDO mapping or the sync manager PDO assignment. In this state the settings for the process data transfer and perhaps terminal-specific parameters that may differ from the default settings are also transferred.

Safe-Operational (Safe-Op)

During transition between Pre-Op and Safe-Op the EtherCAT slave checks whether the sync manager channels for process data communication and, if required, the distributed clocks settings are correct. Before it acknowledges the change of state, the EtherCAT slave copies current input data into the associated DP-RAM areas of the EtherCAT slave controller (ECSC). In Safe-Op state mailbox and process data communication is possible, although the slave keeps its outputs in a safe state, while the input data are updated cyclically

* Note: Outputs in SAFEOP state

The default set watchdog monitoring sets the outputs of the module in a safe state - depending on the settings in SAFEOP and OP - e.g. in OFF state. If this is prevented by deactivation of the watchdog monitoring in the module, the outputs can be switched or set also in the SAFEOP state.

Operational (Op)

Before the EtherCAT master switches the EtherCAT slave from Safe-Op to Op it must transfer valid output data. In the Op state the slave copies the output data of the masters to its outputs. Process data and mailbox communication is possible.

Boot

In the Boot state the slave firmware can be updated. The Boot state can only be reached via the Init state. In the Boot state mailbox communication via the file access over EtherCAT (FoE) protocol is possible, but no other mailbox communication and no process data communication

Ch. **5**

Getting Started

- 5.1 Hardware Preparation and Connection
- 5.2 Software/Development Environment
- 5.3 Connect to your PC and set up the environment
- 5.4 Configuration and Operation
- 5.5 Write the code

This chapter explains how to access the QEC-RXXA Series modules through the <u>QEC-M-01</u> (EtherCAT Master) and its software, <u>86Duino Coding IDE</u>. The parameter settings are easy to configure, shortening the system installation and evaluation time.

Note. QEC's PoE (Power over Ethernet)

In QEC product installations, users can easily distinguish between PoE and non-PoE: if the RJ45 house is red, it is PoE type, and if the RJ45 house is black, it is non-PoE type.





Non-PoE type

PoE type

PoE (Power over Ethernet) is a function that delivers power over the network. QEC can be equipped with an optional PoE function to reduce cabling. In practice, PoE is selected based on system equipment, so please pay attention to the following points while evaluating and testing:

4. When connecting PoE and non-PoE devices, make sure to disconnect Ethernet cables at pins 4, 5, 7, and 8 (e.g., when a PoE-supported QEC EtherCAT master connects with a third-party EtherCAT slave).



5. The PoE function of QEC is different and incompatible with EtherCAT P, and the PoE function of QEC is based on PoE Type B, and the pin functions are as follows:

| | Pin# | Signal Name | Pin# | Signal Name |
|----------|------|-------------|------|-------------|
| | 1 | LAN1_TX+ | 2 | LAN1_TX- |
| <u> </u> | 3 | LAN1_RX+ | 4 | VS+ |
| 8 2,1 | 5 | VP+ | 6 | LAN1_RX- |
| | 7 | VS-(GND) | 8 | VP-(GND) |

^{*} PoE LAN with the Red Housing; Regular LAN with Black Housing.

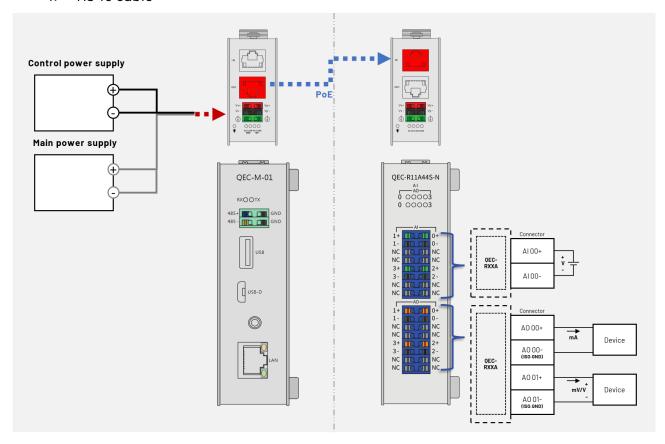
6. QEC's PoE power supply is up to 24V/3A.

^{*}L4, L5, L7, L8 pins are option, for RJ45 Power IN/OUT.

5.1 Hardware Preparation and Connection

The following devices are used here:

- 1. QEC-M-01P (EtherCAT Master/PoE)
- 2. QEC-R11A44S-N (EtherCAT Slave Analog Input and Output/PoE)
- 3. 24V power supplier
- 4. RJ45 cable



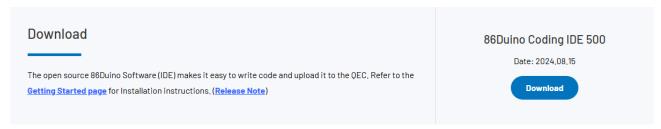
All QEC devices have PoE functions, so we only need to connect to Vs+/Vs and Vp+/Vp power pins (EU terminals) supplies for 19 to 50VDC power on QEC-M-01P, and then other devices will be powered by PoE. After powering on, you'll see the power LED light up and verify that the "PWR" LED indicators are ON (green).



- 1. Using the EtherCAT Out port (top side) connected to the EtherCAT In port of QEC-R11A44S via RJ45 cable (powered by PoE).
- 2. Connect to Vs+/Vs- and Vp+/Vp- power supplies via EU terminals for 24V power.

5.2 Software/Development Environment

Download 86duino IDE from https://www.gec.tw/software/.



About how to update the QEC Master (QEC-M series products) with the latest version of the 86Duino IDE, please see this page.

After downloading, please unzip the downloaded zip file, no additional software installation is required, just double-click **86duino.exe** to start the IDE.



^{*} Note: If Windows displays a warning, click Details once and then click the Continue Run button once.

86Duino Coding IDE 500+ looks like below.

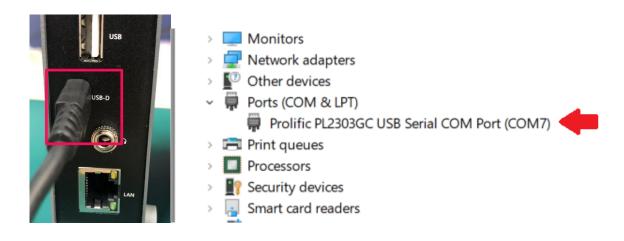


5.3 Connect to your PC and set up the environment

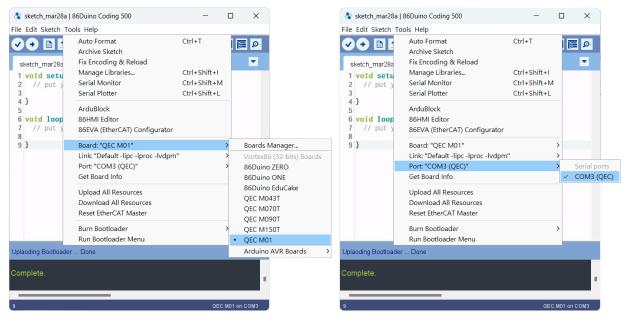
Follow the steps below to set up the environment:

- 1. Connect the QEC-M-01P to your PC via a Micro USB to USB cable (86Duino IDE installed).
- 2. Turn on the QEC power.
- 3. Open "Device Manager" -> "Ports (COM & LPT)" in your PC and expand the ports; you should see that the "Prolific PL2303GC USB Serial COM Port (COMx)" is detected; if not, you will need to install the required drivers.

(For Windows PL2303 driver, you can download here)



- 4. Open the 86Duino IDE.
- 5. Select the correct board: In the IDE's menu, select "Tools" ->" Board"- > QEC-M-01(or the QEC-M master model you use).
- 6. Select Port: In the IDE's menu, select "Tools"->" Port" and select the USB port to connect to the QEC-M master (in this case, COM3 (QEC)).



5.4 Configuration and Operation

This section shows how to operate the EtherCAT Master (QEC-M-01) and QEC-RXXA44S module through the 86Duino IDE's graphical low-code programming tools, 86EVA.

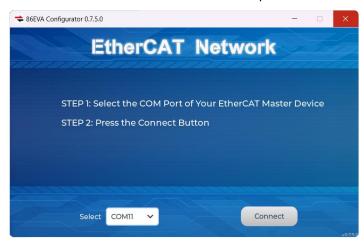
We'll operate the following things:

- 1. Configure Analog Input Range.
- 2. Configure Analog Output Range.
- 3. Read the Analog Input channel 0.
- 4. Write the Analog Output channel 0.

Software Tools Description:

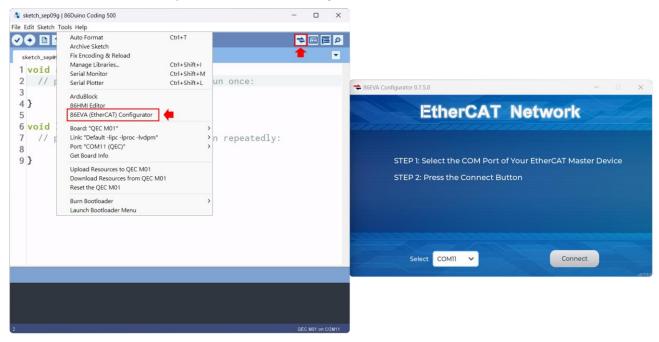
• 86EVA (EVA, EtherCAT-Based Virtual Arduino):

is a graphical EtherCAT configuration tool based on the EtherCAT Library in the 86Duino IDE and is one of the development kits for 86Duino.



Step 1: Turn on 86EVA and scan

The 86EVA tool can be opened via the following buttons.



Once you have confirmed that the correct COM port has been selected of QEC-M-01P, press the "Connect" button to start scanning the EtherCAT network.



The connected devices will be displayed after the EtherCAT network has been scanned. Press the "View" button in the lower left corner to check the device's status (Voltage, Current, and Temperature; View2) and operating time (Hours; View3).



Step 2: Set the parameters

Press twice on the scanned device image to enter the corresponding parameter setting screen.



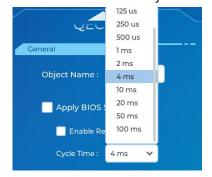
QEC-M-01

Press twice on the image of the QEC-M-01 to see the parameter settings.



Please check the following configures.

- $\hbox{A. Turn off the "Apply BIOS Settings"}.$
- B. Select "4ms" to the Cycle Time.



After the setting and configuration, please click "Back" in the upper left corner to return.



0EC-R11A44S

Press twice on the image of the QEC-R11A44S to see the parameter settings.

In the "General" area, it will show the Object Name, Alias Address, Vendor ID, Product Code, and Firmware about the OEC-R11A44S.



For the Device Information, you can refer to <u>6.2.1 Standard Objects</u> and <u>6.2.2 Manufacturer</u> <u>Objects</u>.

Users can go down of the settings page to the "Range Configuration" area to configure the Analog Input and Analog Output range.

Analog Input:



Input Range: ±22 V; ±20 V; ±11 V; ±10 V; ±5 V; 0 V - 22V; 0 V - 20 V; 0 V - 11 V; 0 V - 10 V



In this case, we select -22V ~ 22V.

Analog Output:



Output Current: 0 mA - 24 mA; 3.5 mA - 23.5 mA; 0 mA - 20 mA; 4 mA - 20 mA; $\pm 24 \text{ mA}$. Output Voltage: 0 V - 5 V; 0 V - 10 V; $\pm 5 \text{ V}$; $\pm 10 \text{ V}$; - 0 V - 6 V; 0 V - 12 V; $\pm 6 \text{ V}$; $\pm 12 \text{ V}$.

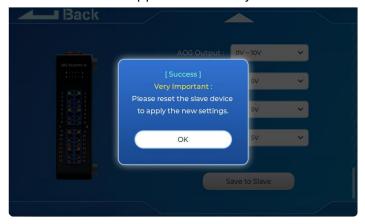


In this case, we select $0V \sim 10V$.

After setting the Analog IO range configuration, please click the "Save to Slave" button so your settings will be written into the QEC-R11A44S after you reboot its power.



The windows will appear to notice you need to reset the device.



Step 3: Generate the code

After configuring all settings, click the "Code Generation" button.



After clicking, the result and completion screen will appear, click OK to leave the program; If you do not click OK, you will leave the program after 10 seconds.



The generated code and files are as follows:

- sketch_sep30a: Main Project (depends on your project name)
- ChatGPT.h: Parameters to provide to ChatGPT referred
- myeva.cpp: C++ program code of 86EVA
- myeva.h: Header file of 86EVA

```
💲 sketch_sep30a | 86Duino Coding 500
                                                                       X
File Edit Sketch Tools Help
√(+) □ ± ±
                                                                      GPT.h
  sketch_sep30a
                       myeva.cpp
                                  myeva.h
 1 #include "myeva.h"
 2 void setup() {
     EVA.begin();
 3
 4
     // put your setup code here, to run once:
 5
 6 }
 8 void loop() {
   // put your main code here, to run repeatedly:
10
11 }
```

- * Additional note: After 86EVA generates code, the following code will be automatically generated in the main program (.ino), and any of them missing will cause 86EVA not to work.
- 1. #include "myeva.h": Include EVA Header file
- 2. EVA.begin(); in setup(): Initialize the EVA function

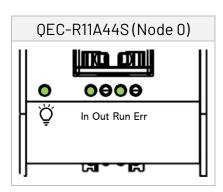
Step 4: Upload the code

Once the code is generated, click on the toolbar to compile, and to confirm that the compilation is complete and error-free, you can click to upload. The program will run when the upload is complete.



After the upload, if the EtherCAT Network is running successfully, it will enter OPERATION mode.

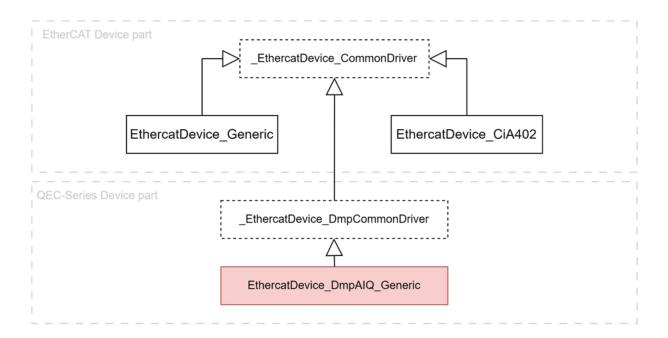
You can confirm this by the RUN LED on your QEC slave device, which should light up. Additionally, the LED on the EtherCAT LAN ports will start blinking, indicating active operation.



5.5 Write the code

In this section, we will operate the EthercatDevice_DmpAlQ_Generic Class to control QEC-R11A44S.

The EthercatDevice_DmpAlQ_Generic is an EtherCAT slave class specifically developed by ICOP for Analog I/O EtherCAT slave modules. It provides APIs for analog input, analog output, and other functionalities.



To effectively utilize your EtherCAT device, it's important to understand which functions are compatible with different modules (For EtherCAT Slave index assignments, please refer to <u>6.2.3 Function Objects</u>).

Analog Output Functions

Analog output functions for the EthercatDevice_DmpAlQ_Generic class.

- analogWrite()
- voltageWrite()
- currentWrite()

Analog Input Functions

Analog input functions for the EthercatDevice_DmpAIQ_Generic class.

- analogRead()
- voltageRead()

5.5.1 Examples

When using these functions, reference the Object Name of your QEC device as set in the 86FVA.



The programming code from 86EVA are set as the following by default:

- QEC-M-01: EthercatMaster object.
- QEC-R11A44S device: EthercatDevice_DmpAlQ_Generic object.
- EtherCAT mode: ECAT_SYNC.

And here is the setting by users:

- EtherCAT Cycle time: 4 milisecond.
- Device Object Name: QEC-M-01 is "EcatMaster", and QEC-R11A44S is "Slave0".

1. In Setup Function:

- Initializes the serial (115200).
- Use EVA.begin(); to initialize the EtherCAT system.

2. In Loop Function:

- Reads the voltage value from Analog Input Channel O(AlOO) using
 SlaveO.voltageRead(O); and prints the result to the serial monitor.
 This gives continuous feedback on the input voltage.
- Use Slave.voltageWrite(0, 10); for Analog Output Channel O(AOOO) output 10V.
- Use delay(10); to wait for stability.

In summary, this example code initializes communication with the QEC-R11A44S-N module, reads the analog input voltage, and sets an output voltage. It continuously prints the input voltage to the serial monitor, demonstrating basic analog signal acquisition and control using the module.

Code Example:

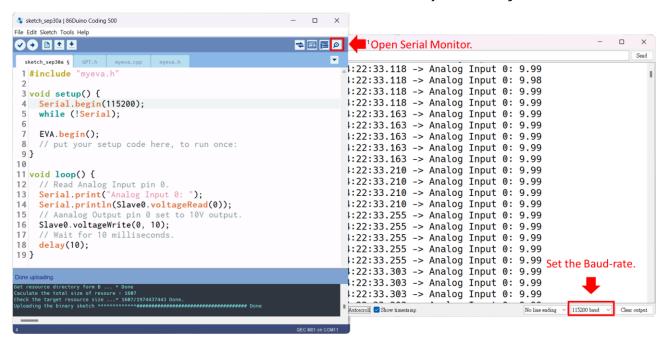
```
#include "myeva.h" // Include the necessary library for EVA control.
void setup() {
 // Start serial communication with a baud rate of 115200.
 Serial.begin(115200);
 while (!Serial); // Wait for the serial port to connect.
 // Initialize the QEC system.
 EVA.begin();
}
void loop() {
 // Read the voltage from Analog Input pin 0.
 Serial.print("Analog Input 0: ");
 Serial.println(Slave0.voltageRead(0)); // Print the analog input value
from pin 0 to the serial monitor.
 // Set Analog Output pin 0 to 10V.
 Slave.voltageWrite(0, 10);
 // Wait for 10 milliseconds before continuing.
 delay(10);
```

Note:

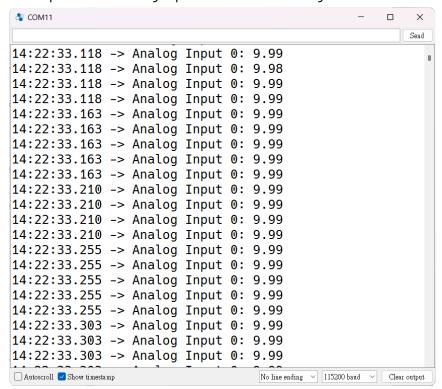
Once the code is written, click on the toolbar to \bigcirc compile, and to confirm that the compilation is complete and error-free, you can click \bigcirc to upload. The program will run when the upload is complete.



After you successfully upload the program to the QEC-M-01, you can open the Serial Monitor on 86Duino IDE. Please check the Serial baud rate is same as your setting.



It will print the Analog Input channel 0's voltage value to the serial monitor.



5.5.2 Access Further Documentation

For a comprehensive understanding of the EtherCAT Master API, please refer to the EtherCAT Master API User Manual. This manual provides an in-depth overview of the API, detailing advanced features and capabilities to enhance your experience with EtherCAT technology.

For further exploration of programming beyond the basic setup, we recommend consulting the Language Reference Home and Libraries Reference Home. These resources offer extensive information on programming functions and libraries related to EtherCAT, supporting both beginner and advanced users.

To access the full EtherCAT Master API User Manual, please contact our sales team or email us at info@icop.com.tw. Our dedicated team is here to support you with detailed information and assistance for all your needs.

For online documentation, you can also visit:

 EtherCAT Library API User Manual: https://www.qec.tw/ethercat/api/ethercat-library-api-user-manual/

For further inquiries or sample requests, feel free to:

- Email: info@icop.com.tw
- Call your nearest ICOP branch or
- Contact our Worldwide Official Distributor.

Ch. **6**

Slave Information

6.1 ESI (EtherCAT Slave Information) file

6.2 Object Dictionary

6.1 ESI (EtherCAT Slave Information) file

The ESI files contain information unique to the EtherCAT Slave Terminals in XML format. You can load an ESI file into the Support Software to easily allocate Slave Terminal process data and other settings. The ESI files for QEC EtherCAT slaves are already installed in the Support Software.

Note. Ensuring Up-to-date Installation of the XML Device Description File (ESI)

To ensure smooth functioning, it is important to install the latest version of the XML device description file in the EtherCAT Master software. The latest version of the XML device description file can be downloaded from the OEC website.

https://www.qec.tw/

6.2 Object Dictionary

The object dictionary defined here shall be used complementary with ETG.5001 and FTG.1000.

Device Profile: 5001

Modul Profile: 0

Usage Notes:

- The PDO mapping object and SyncManager assignment object doesn't need to be defined. In that case they are created automatically.
- The following objects are fixed included in the SSC and shall not be defined in the file: 0x1000, 0x1001, 0x1008, 0x1009, 0x100a, 0x1010, 0x1011, 0x1018, 0x10F0, 0x10F1, 0x10F3, 0x1c00, 0x1c32, 0x1c33
- Entries less or equal one 8Bit shall not overlap byte borders.
- Entries greater 8Bit shall always start at an exact word border

6.2.1 Standard Objects

Index 1000 Device type

| Index | Name | Data type | Flags | Default |
|-------|-------------|-----------|-------|---------------------|
| 1000 | Device type | UINT32 | RO | 0x00040192 (262546) |

Index 1001 Error register

| Index | Name | Data type | Flags | Default |
|-------|----------------|-----------|-------|---------|
| 1001 | Error register | UINT8 | RO | 0x00(0) |

Index 1008 Device name

| Index | Name | Data type | Flags | Default |
|-------|-------------|-----------|-------|---------------------------|
| 1008 | Device name | STRING | RO | Refer to following table. |

Table 4-1: Device Name

| Туре | Device Name |
|---|-------------|
| Analog Input 8-slot | QEC-ROOA80S |
| Analog Input 8-slot (PoE) | QEC-R11A80S |
| Analog Input 4-slot, Analog Output 4-slot | QEC-R00A44S |
| Analog Input 4-slot, Analog Output 4-slot (PoE) | QEC-R11A44S |
| Analog Output 8-slot | QEC-R00A08S |
| Analog Output 8-slot | QEC-R11A08S |

Index 1009 Hardware version

| Index | Name | Data type | Flags | Default |
|-------|----------------------|-----------|-------|-------------------------------|
| 1009 | Hardware version | STRING | RO | Depends on the version of the |
| 1009 | nai uwai e vei sioii | | | product you have. |

Index 100A Software version

| Index | Name | Data type | Flags | Default |
|-------|------------------|-----------|-------|-------------------------------|
| 100A | 0-4 | OTRINO | RO | Depends on the version of the |
| IUUA | Software version | STRING | | product you have. |

Index 1018 Identity

| Index | Name | Data type | Flags | Default |
|---------|---------------|-----------|-------|---------------------------|
| 1018:0 | Identity | UINT8 | RO | >4< |
| 1018:01 | Vendor ID | UINT32 | RO | 0x00000BC3 (3011) |
| 1018:02 | Product code | UINT32 | RO | Refer to following table. |
| 1018:03 | Revision | UINT32 | RO | Depending by model. |
| 1018:04 | Serial number | UINT32 | RO | 0x00000001(1) |

Table 4-3: Product code & Revision Number

| Model Name | Product code |
|-------------|--------------|
| QEC-R11A44S | 0x0086d880 |

Index 10F1 Error Settings

| Index | Name | Data type | Flags | Default |
|---------|--------------------------|-----------|-------|--------------|
| 10F1:0 | Error Settings | UINT8 | RO | >2< |
| 10F1:01 | Local Error Reaction | UINT32 | RW | 0x0000001(1) |
| 10F1:02 | Sync Error Counter Limit | UINT32 | RW | 0x0004(4) |

Index 10F8 Timestamp Object

| Index | Name | Data type | Flags | Default |
|-------|------------------|-----------|-------|-------------------------|
| 10F8 | Timestamp Object | UINT64 | RW P | 9E 04 CA F3 20 00 00 00 |

6.2.2 Manufacturer Objects

Index 0x5xxn Manufacturer Objects

| Index | Name | Data type | Flags | Default |
|---------|------------------|-------------|-------|---------|
| 5000 | SP_Voltage | UINT16 | RW | 0 |
| 5001 | SP_Current | UINT16 | RW | 0 |
| 5002 | PP_Voltage | UINT16 | RW | 0 |
| 5003 | PP_Current | UINT16 | RW | 0 |
| 5004 | Temperature | INT16 | RW | 0 |
| 5005 | BoxStatus | UINT8 | RW | 0 |
| 5006 | OrderInformation | - | - | >4< |
| 5006:01 | Customer | STRING(6) | RO | - |
| 5006:02 | OrderNo | STRING(8) | RO | - |
| 5006:03 | InvNo | STRING (11) | RO | - |
| 5006:04 | DelyDate | STRING (14) | RO | - |
| 5007 | MTBF | - | - | >2< |
| 5007:01 | WorkingHours | INT32 | RO | 0 |
| 5007:02 | BootTimes | INT32 | RO | 0 |

6.2.3 Function Objects

The following objects correspond to each analog input and output slot, providing a range of settings for status, voltage range, threshold levels, and resolution.

- Analog Input Slots (Index 0x5010~0x5017)
- Analog Output Slots (Index 0x5020~0x5027)

Index 0x5010 Analog Input 0

The configuration objects allow for the setup of operational parameters such as voltage range, threshold values, and resolution for precise data acquisition.

| Index | Name | Data type | Flags | Default |
|---------|-------------------------|-----------|-------|---------|
| 5010:0 | AnalogInput0 | - | TX | - |
| 5010:01 | Status | UINT16 | RO | 0 |
| 5010:02 | Range | UINT8 | RW | 0 |
| 5010:03 | Threshold_of_Input_High | UINT16 | RW | 0xFFFF |
| 5010:04 | Threshold_of_Input_Low | UINT16 | RW | 0 |
| 5010:05 | Resolution | REAL32 | RO | 0 |

The Status object (Index 0x5010:01) shows the current condition of the analog input. It is divided into several bits that indicate specific issues:

- Bit 0: Input To Low By subindex 4
- Bit 1: Input To High By subindex 4
- Bit 2: AVDD low
- Bit 3: AVDD High

The Range object (Index 0x5010:02) offers multiple predefined voltage settings, allowing the module to be adapted for various voltage inputs:

- 0000b: Full voltage ≒ ±22V
- 0001b: Full voltage $= \pm 20V$
- 0010b: Full voltage $= \pm 11V$
- 0011b: Full voltage $= \pm 10V$
- 0100b: Full voltage $= \pm 5V$
- 0101b: Full voltage ≒ 22V
- 0110b: Full voltage ≒ 20V
- 0111b: Full voltage ≒ 11V
- 1000b: Full voltage ≒ 10V

Index 0x5011 Analog Input 1

The configuration objects allow for the setup of operational parameters such as voltage range, threshold values, and resolution for precise data acquisition.

| Index | Name | Data type | Flags | Default |
|---------|-------------------------|-----------|-------|---------|
| 5011:0 | AnalogInput1 | - | TX | - |
| 5011:01 | Status | UINT16 | RO | 0 |
| 5011:02 | Range | UINT8 | RW | 0 |
| 5011:03 | Threshold_of_Input_High | UINT16 | RW | 0xFFFF |
| 5011:04 | Threshold_of_Input_Low | UINT16 | RW | 0 |
| 5011:05 | Resolution | REAL32 | RO | 0 |

The Status object (Index 0x5011:01) shows the current condition of the analog input. It is divided into several bits that indicate specific issues:

• Bit 0: Input To Low By subindex 4

• Bit 1: Input To High By subindex 4

Bit 2: AVDD low

• Bit 3: AVDD High

The Range object (Index 0x5011:02) offers multiple predefined voltage settings, allowing the module to be adapted for various voltage inputs:

• 0000b: Full voltage $= \pm 22V$

• 0001b: Full voltage $= \pm 20V$

• 0010b: Full voltage $= \pm 11V$

• 0011b: Full voltage $= \pm 10V$

0100b: Full voltage ≒ ±5V

• 0101b: Full voltage = 22V

• 0110b: Full voltage ≒ 20V

• 0111b: Full voltage = 11V

• 1000b: Full voltage ≒ 10V

Index 0x5012 Analog Input 2

The configuration objects allow for the setup of operational parameters such as voltage range, threshold values, and resolution for precise data acquisition.

| Index | Name | Data type | Flags | Default |
|---------|-------------------------|-----------|-------|---------|
| 5012:0 | AnalogInput2 | - | TX | - |
| 5012:01 | Status | UINT16 | RO | 0 |
| 5012:02 | Range | UINT8 | RW | 0 |
| 5012:03 | Threshold_of_Input_High | UINT16 | RW | 0xFFFF |
| 5012:04 | Threshold_of_Input_Low | UINT16 | RW | 0 |
| 5012:05 | Resolution | REAL32 | RO | 0 |

The Status object (Index 0x5012:01) shows the current condition of the analog input. It is divided into several bits that indicate specific issues:

• Bit 0: Input To Low By subindex 4

Bit 1: Input To High By subindex 4

Bit 2: AVDD low

• Bit 3: AVDD High

The Range object (Index 0x5012:02) offers multiple predefined voltage settings, allowing the module to be adapted for various voltage inputs:

• 0000b: Full voltage $= \pm 22V$

• 0001b: Full voltage $= \pm 20V$

• 0010b: Full voltage $= \pm 11V$

• 0011b: Full voltage $= \pm 10V$

0100b: Full voltage ≒ ±5V

• 0101b: Full voltage = 22V

• 0110b: Full voltage ≒ 20V

• 0111b: Full voltage = 11V

• 1000b: Full voltage ≒ 10V

Index 0x5013 Analog Input 3

The configuration objects allow for the setup of operational parameters such as voltage range, threshold values, and resolution for precise data acquisition.

| Index | Name | Data type | Flags | Default |
|---------|-------------------------|-----------|-------|---------|
| 5013:0 | AnalogInput3 | - | TX | - |
| 5013:01 | Status | UINT16 | RO | 0 |
| 5013:02 | Range | UINT8 | RW | 0 |
| 5013:03 | Threshold_of_Input_High | UINT16 | RW | 0xFFFF |
| 5013:04 | Threshold_of_Input_Low | UINT16 | RW | 0 |
| 5013:05 | Resolution | REAL32 | RO | 0 |

The Status object (Index 0x5013:01) shows the current condition of the analog input. It is divided into several bits that indicate specific issues:

• Bit 0: Input To Low By subindex 4

Bit 1: Input To High By subindex 4

Bit 2: AVDD low

• Bit 3: AVDD High

The Range object (Index 0x5013:02) offers multiple predefined voltage settings, allowing the module to be adapted for various voltage inputs:

• 0000b: Full voltage $= \pm 22V$

• 0001b: Full voltage $= \pm 20V$

• 0010b: Full voltage $= \pm 11V$

• 0011b: Full voltage $= \pm 10V$

• 0100b: Full voltage $= \pm 5V$

• 0101b: Full voltage ≒ 22V

• 0110b: Full voltage ≒ 20V

• 0111b: Full voltage = 11V

• 1000b: Full voltage ≒ 10V

Index 0x5014 Analog Input 4

The configuration objects allow for the setup of operational parameters such as voltage range, threshold values, and resolution for precise data acquisition.

| Index | Name | Data type | Flags | Default |
|---------|-------------------------|-----------|-------|---------|
| 5014:0 | AnalogInput4 | - | TX | - |
| 5014:01 | Status | UINT16 | RO | 0 |
| 5014:02 | Range | UINT8 | RW | 0 |
| 5014:03 | Threshold_of_Input_High | UINT16 | RW | 0xFFFF |
| 5014:04 | Threshold_of_Input_Low | UINT16 | RW | 0 |
| 5014:05 | Resolution | REAL32 | RO | 0 |

The Status object (Index 0x5014:01) shows the current condition of the analog input. It is divided into several bits that indicate specific issues:

• Bit 0: Input To Low By subindex 4

• Bit 1: Input To High By subindex 4

Bit 2: AVDD low

• Bit 3: AVDD High

The Range object (Index 0x5014:02) offers multiple predefined voltage settings, allowing the module to be adapted for various voltage inputs:

• 0000b: Full voltage $= \pm 22V$

• 0001b: Full voltage $= \pm 20V$

• 0010b: Full voltage $= \pm 11V$

• 0011b: Full voltage $= \pm 10V$

• 0100b: Full voltage $= \pm 5V$

• 0101b: Full voltage ≒ 22V

• 0110b: Full voltage ≒ 20V

• 0111b: Full voltage = 11V

• 1000b: Full voltage ≒ 10V

Index 0x5015 Analog Input 5

The configuration objects allow for the setup of operational parameters such as voltage range, threshold values, and resolution for precise data acquisition.

| Index | Name | Data type | Flags | Default |
|---------|-------------------------|-----------|-------|---------|
| 5015:0 | AnalogInput5 | - | TX | - |
| 5015:01 | Status | UINT16 | RO | 0 |
| 5015:02 | Range | UINT8 | RW | 0 |
| 5015:03 | Threshold_of_Input_High | UINT16 | RW | 0xFFFF |
| 5015:04 | Threshold_of_Input_Low | UINT16 | RW | 0 |
| 5015:05 | Resolution | REAL32 | RO | 0 |

The Status object (Index 0x5015:01) shows the current condition of the analog input. It is divided into several bits that indicate specific issues:

• Bit 0: Input To Low By subindex 4

• Bit 1: Input To High By subindex 4

Bit 2: AVDD low

• Bit 3: AVDD High

The Range object (Index 0x5015:02) offers multiple predefined voltage settings, allowing the module to be adapted for various voltage inputs:

• 0000b: Full voltage $= \pm 22V$

• 0001b: Full voltage $= \pm 20V$

• 0010b: Full voltage $= \pm 11V$

• 0011b: Full voltage $= \pm 10V$

• 0100b: Full voltage $= \pm 5V$

• 0101b: Full voltage ≒ 22V

• 0110b: Full voltage ≒ 20V

• 0111b: Full voltage = 11V

• 1000b: Full voltage ≒ 10V

Index 0x5016 Analog Input 6

The configuration objects allow for the setup of operational parameters such as voltage range, threshold values, and resolution for precise data acquisition.

| Index | Name | Data type | Flags | Default |
|---------|-------------------------|-----------|-------|---------|
| 5016:0 | AnalogInput6 | - | TX | - |
| 5016:01 | Status | UINT16 | RO | 0 |
| 5016:02 | Range | UINT8 | RW | 0 |
| 5016:03 | Threshold_of_Input_High | UINT16 | RW | 0xFFFF |
| 5016:04 | Threshold_of_Input_Low | UINT16 | RW | 0 |
| 5016:05 | Resolution | REAL32 | RO | 0 |

The Status object (Index 0x5016:01) shows the current condition of the analog input. It is divided into several bits that indicate specific issues:

• Bit 0: Input To Low By subindex 4

• Bit 1: Input To High By subindex 4

• Bit 2: AVDD low

• Bit 3: AVDD High

The Range object (Index 0x5016:02) offers multiple predefined voltage settings, allowing the module to be adapted for various voltage inputs:

• 0000b: Full voltage ≒ ±22V

• 0001b: Full voltage $= \pm 20V$

• 0010b: Full voltage $= \pm 11V$

• 0011b: Full voltage $= \pm 10V$

0100b: Full voltage ≒ ±5V

• 0101b: Full voltage = 22V

• 0110b: Full voltage ≒ 20V

• 0111b: Full voltage = 11V

• 1000b: Full voltage ≒ 10V

Index 0x5017 Analog Input 7

The configuration objects allow for the setup of operational parameters such as voltage range, threshold values, and resolution for precise data acquisition.

| Index | Name | Data type | Flags | Default |
|---------|-------------------------|-----------|-------|---------|
| 5017:0 | AnalogInput7 | - | TX | - |
| 5017:01 | Status | UINT16 | RO | 0 |
| 5017:02 | Range | UINT8 | RW | 0 |
| 5017:03 | Threshold_of_Input_High | UINT16 | RW | 0xFFFF |
| 5017:04 | Threshold_of_Input_Low | UINT16 | RW | 0 |
| 5017:05 | Resolution | REAL32 | RO | 0 |

The Status object (Index 0x5017:01) shows the current condition of the analog input. It is divided into several bits that indicate specific issues:

• Bit 0: Input To Low By subindex 4

• Bit 1: Input To High By subindex 4

• Bit 2: AVDD low

• Bit 3: AVDD High

The Range object (Index 0x5017:02) offers multiple predefined voltage settings, allowing the module to be adapted for various voltage inputs:

• 0000b: Full voltage $= \pm 22V$

• 0001b: Full voltage $= \pm 20V$

• 0010b: Full voltage $= \pm 11V$

• 0011b: Full voltage $= \pm 10V$

0100b: Full voltage ≒ ±5V

• 0101b: Full voltage = 22V

• 0110b: Full voltage ≒ 20V

• 0111b: Full voltage = 11V

• 1000b: Full voltage ≒ 10V

Index 0x5020 Digital Output 0

Index 0x5020 is designated for configuring digital output operations in the QEC-RXXA series module. The configuration objects allow for setting operational parameters such as voltage range, threshold values, and resolution.

| Index | Name | Data type | Flags | Default |
|---------|----------------|-----------|-------|---------|
| 5020:0 | DigitalOutput0 | - | TX | - |
| 5020:01 | Status | UINT16 | RO | 0 |
| 5020:02 | Range | UINT8 | RW | 0 |

DAC Output Range Settings (Index 5020:02):

This module supports a variety of output ranges, both in voltage and current modes, which can be configured through the Range object to meet diverse application needs:

Voltage Output Settings:

o 0000: 0 to +5 V (default)

o 0001: 0 to +10 V

o 0010: ±5 V

o 0011: ±10 V

o 1000: 0 to +6 V

o 1001: 0 to +12 V

o 1010: ±6 V

o 1011: ±12 V

• Current Output Settings:

o 0100: 3.5 mA to 23.5 mA

o 0101: 0 to 20 mA

o 0110: 0 to 24 mA

o 0111: ±24 mA

o 1100: 4 mA to 20 mA

Any setting outside these specified ranges will disable the output.

Index 0x5021 Digital Output 1

Index 0x5021 is designated for configuring digital output operations in the QEC-RXXA series module. The configuration objects allow for setting operational parameters such as voltage range, threshold values, and resolution.

| Index | Name | Data type | Flags | Default |
|---------|----------------|-----------|-------|---------|
| 5021:0 | DigitalOutput1 | - | TX | - |
| 5021:01 | Status | UINT16 | RO | 0 |
| 5021:02 | Range | UINT8 | RW | 0 |

DAC Output Range Settings (Index 5021:02):

This module supports a variety of output ranges, both in voltage and current modes, which can be configured through the Range object to meet diverse application needs:

• Voltage Output Settings:

o 0000: 0 to +5 V (default)

o 0001: 0 to +10 V

 $\circ \quad 0010 \colon \pm 5 \ V$

o 0011: ±10 V

o 1000: 0 to +6 V

o 1001: 0 to +12 V

o 1010: ±6 V

o 1011: ±12 V

• Current Output Settings:

o 0100: 3.5 mA to 23.5 mA

o 0101: 0 to 20 mA

o 0110: 0 to 24 mA

o 0111: ±24 mA

o 1100: 4 mA to 20 mA

Any setting outside these specified ranges will disable the output.

Index 0x5022 Digital Output 2

Index 0x5022 is designated for configuring digital output operations in the QEC-RXXA series module. The configuration objects allow for setting operational parameters such as voltage range, threshold values, and resolution.

| Index | Name | Data type | Flags | Default |
|---------|----------------|-----------|-------|---------|
| 5022:0 | DigitalOutput2 | - | TX | - |
| 5022:01 | Status | UINT16 | RO | 0 |
| 5022:02 | Range | UINT8 | RW | 0 |

DAC Output Range Settings (Index 5022:02):

This module supports a variety of output ranges, both in voltage and current modes, which can be configured through the Range object to meet diverse application needs:

• Voltage Output Settings:

o 0000: 0 to +5 V (default)

o 0001: 0 to +10 V

o 0010: ±5 V

o 0011: ±10 V

o 1000: 0 to +6 V

o 1001: 0 to +12 V

o 1010: ±6 V

o 1011: ±12 V

• Current Output Settings:

o 0100: 3.5 mA to 23.5 mA

o 0101: 0 to 20 mA

o 0110: 0 to 24 mA

o 0111: ±24 mA

o 1100: 4 mA to 20 mA

Any setting outside these specified ranges will disable the output.

Index 0x5023 Digital Output 3

Index 0x5023 is designated for configuring digital output operations in the QEC-RXXA series module. The configuration objects allow for setting operational parameters such as voltage range, threshold values, and resolution.

| Index | Name | Data type | Flags | Default |
|---------|----------------|-----------|-------|---------|
| 5023:0 | DigitalOutput3 | - | TX | - |
| 5023:01 | Status | UINT16 | RO | 0 |
| 5023:02 | Range | UINT8 | RW | 0 |

DAC Output Range Settings (Index 5023:02):

This module supports a variety of output ranges, both in voltage and current modes, which can be configured through the Range object to meet diverse application needs:

• Voltage Output Settings:

o 0000: 0 to +5 V (default)

o 0001: 0 to +10 V

o 0010: ±5 V

o 0011: ±10 V

o 1000: 0 to +6 V

o 1001: 0 to +12 V

o 1010: ±6 V

o 1011: ±12 V

• Current Output Settings:

o 0100: 3.5 mA to 23.5 mA

o 0101: 0 to 20 mA

o 0110: 0 to 24 mA

o 0111: ±24 mA

o 1100: 4 mA to 20 mA

Any setting outside these specified ranges will disable the output.

Index 0x5024 Digital Output 4

Index 0x5024 is designated for configuring digital output operations in the QEC-RXXA series module. The configuration objects allow for setting operational parameters such as voltage range, threshold values, and resolution.

| Index | Name | Data type | Flags | Default |
|---------|----------------|-----------|-------|---------|
| 5024:0 | DigitalOutput4 | - | TX | - |
| 5024:01 | Status | UINT16 | RO | 0 |
| 5024:02 | Range | UINT8 | RW | 0 |

DAC Output Range Settings (Index 5024:02):

This module supports a variety of output ranges, both in voltage and current modes, which can be configured through the Range object to meet diverse application needs:

• Voltage Output Settings:

o 0000: 0 to +5 V (default)

o 0001: 0 to +10 V

o 0010: ±5 V

o 0011: ±10 V

o 1000: 0 to +6 V

o 1001: 0 to +12 V

o 1010: ±6 V

o 1011: ±12 V

• Current Output Settings:

o 0100: 3.5 mA to 23.5 mA

o 0101: 0 to 20 mA

o 0110: 0 to 24 mA

o 0111: ±24 mA

o 1100: 4 mA to 20 mA

Any setting outside these specified ranges will disable the output.

Index 0x5025 Digital Output 5

Index 0x5025 is designated for configuring digital output operations in the QEC-RXXA series module. The configuration objects allow for setting operational parameters such as voltage range, threshold values, and resolution.

| Index | Name | Data type | Flags | Default |
|---------|----------------|-----------|-------|---------|
| 5025:0 | DigitalOutput5 | - | TX | - |
| 5025:01 | Status | UINT16 | RO | 0 |
| 5025:02 | Range | UINT8 | RW | 0 |

DAC Output Range Settings (Index 5025:02):

This module supports a variety of output ranges, both in voltage and current modes, which can be configured through the Range object to meet diverse application needs:

• Voltage Output Settings:

o 0000: 0 to +5 V (default)

o 0001: 0 to +10 V

o 0010: ±5 V

o 0011: ±10 V

o 1000: 0 to +6 V

o 1001: 0 to +12 V

o 1010: ±6 V

o 1011: ±12 V

• Current Output Settings:

o 0100: 3.5 mA to 23.5 mA

o 0101: 0 to 20 mA

o 0110: 0 to 24 mA

o 0111: ±24 mA

o 1100: 4 mA to 20 mA

Any setting outside these specified ranges will disable the output.

Index 0x5026 Digital Output 6

Index 0x5026 is designated for configuring digital output operations in the QEC-RXXA series module. The configuration objects allow for setting operational parameters such as voltage range, threshold values, and resolution.

| Index | Name | Data type | Flags | Default |
|---------|----------------|-----------|-------|---------|
| 5026:0 | DigitalOutput6 | - | TX | - |
| 5026:01 | Status | UINT16 | RO | 0 |
| 5026:02 | Range | UINT8 | RW | 0 |

DAC Output Range Settings (Index 5026:02):

This module supports a variety of output ranges, both in voltage and current modes, which can be configured through the Range object to meet diverse application needs:

• Voltage Output Settings:

o 0000: 0 to +5 V (default)

o 0001: 0 to +10 V

o 0010: ±5 V

o 0011: ±10 V

o 1000: 0 to +6 V

o 1001: 0 to +12 V

o 1010: ±6 V

o 1011: ±12 V

• Current Output Settings:

o 0100: 3.5 mA to 23.5 mA

o 0101: 0 to 20 mA

o 0110: 0 to 24 mA

o 0111: ±24 mA

o 1100: 4 mA to 20 mA

Any setting outside these specified ranges will disable the output.

Index 0x5027 Digital Output 7

Index 0x5027 is designated for configuring digital output operations in the QEC-RXXA series module. The configuration objects allow for setting operational parameters such as voltage range, threshold values, and resolution.

| Index | Name | Data type | Flags | Default |
|---------|----------------|-----------|-------|---------|
| 5027:0 | DigitalOutput7 | - | TX | - |
| 5027:01 | Status | UINT16 | RO | 0 |
| 5027:02 | Range | UINT8 | RW | 0 |

DAC Output Range Settings (Index 5027:02):

This module supports a variety of output ranges, both in voltage and current modes, which can be configured through the Range object to meet diverse application needs:

• Voltage Output Settings:

o 0000: 0 to +5 V (default)

o 0001: 0 to +10 V

o 0010: ±5 V

o 0011: ±10 V

o 1000: 0 to +6 V

o 1001: 0 to +12 V

o 1010: ±6 V

o 1011: ±12 V

• Current Output Settings:

o 0100: 3.5 mA to 23.5 mA

o 0101: 0 to 20 mA

o 0110: 0 to 24 mA

o 0111: ±24 mA

o 1100: 4 mA to 20 mA

Any setting outside these specified ranges will disable the output.

6.2.4 Especial Objects (0x6000-0xFFFF)

Index 0x6nnx Input Data of the Module (0x6000 - 0x6FFF)

This section of the object dictionary defines the input data for the module, focusing on the analog input channels. Each index represents a unique analog input, with corresponding resolution settings and data conversion formulas for accurate signal acquisition.

Index 0x6000 Analog Input 0

| Index | Name | Data type | Flags | Default |
|-------|--------------|-----------|-------|---------|
| 6000 | AnalogInput0 | UINT16 | RO | - |

- For ranges 0, 1, 2, 3, 4: $Vin = (AnalogInput0 - 32768) \times Resolution$
- For ranges 5, 6, 7, 8:
 Vin = (AnalogInput0) × Resolution

Resolution is specified at 0x5010:05.

Index 0x6001 Analog Input 1

| Index | Name | Data type | Flags | Default |
|-------|--------------|-----------|-------|---------|
| 6001 | AnalogInput1 | UINT16 | RO | - |

- For ranges 0, 1, 2, 3, 4: $Vin = (AnalogInput0 - 32768) \times Resolution$
- For ranges 5, 6, 7, 8: $Vin = (AnalogInput0) \times Resolution$

Resolution is specified at 0x5011:05.

Index 0x6002 Analog Input 2

| Index | Name | Data type | Flags | Default | |
|-------|--------------|-----------|-------|---------|--|
| 6002 | AnalogInput2 | UINT16 | RO | - | |

• For ranges 0, 1, 2, 3, 4: $Vin = (AnalogInput0 - 32768) \times Resolution$

For ranges 5, 6, 7, 8:
 Vin = (AnalogInput0) × Resolution

Resolution is specified at 0x5012:05.

Index 0x6003 Analog Input 3

| Index | Name | Data type | Flags | Default |
|-------|--------------|-----------|-------|---------|
| 6003 | AnalogInput3 | UINT16 | RO | - |

• For ranges 0, 1, 2, 3, 4: $Vin = (AnalogInput0 - 32768) \times Resolution$

• For ranges 5, 6, 7, 8: $Vin = (AnalogInput0) \times Resolution$

Resolution is specified at 0x5013:05.

Index 0x6004 Analog Input 4

| Index | Name | Data type | Flags | Default |
|-------|--------------|-----------|-------|---------|
| 6004 | AnalogInput4 | UINT16 | RO | - |

• For ranges 0, 1, 2, 3, 4: $Vin = (AnalogInput0 - 32768) \times Resolution$

• For ranges 5, 6, 7, 8: $Vin = (AnalogInput0) \times Resolution$

Resolution is specified at 0x5014:05.

Index 0x6005 Analog Input 5

| Index | Name | Data type | Flags | Default | |
|-------|--------------|-----------|-------|---------|--|
| 6005 | AnalogInput5 | UINT16 | RO | - | |

• For ranges 0, 1, 2, 3, 4: $Vin = (AnalogInput0 - 32768) \times Resolution$

• For ranges 5, 6, 7, 8: $Vin = (AnalogInput0) \times Resolution$

Resolution is specified at 0x5015:05.

Index 0x6006 Analog Input 6

| Index | Name | Data type | Flags | Default |
|-------|--------------|-----------|-------|---------|
| 6006 | AnalogInput6 | UINT16 | RO | - |

• For ranges 0, 1, 2, 3, 4: $Vin = (AnalogInput0 - 32768) \times Resolution$

• For ranges 5, 6, 7, 8: $Vin = (AnalogInput0) \times Resolution$

Resolution is specified at 0x5016:05.

Index 0x6007 Analog Input 7

| Index | Name | Data type | Flags | Default |
|-------|--------------|-----------|-------|---------|
| 6007 | AnalogInput7 | UINT16 | RO | - |

• For ranges 0, 1, 2, 3, 4: $Vin = (AnalogInput0 - 32768) \times Resolution$

For ranges 5, 6, 7, 8:
 Vin = (AnalogInput0) × Resolution

Resolution is specified at 0x5017:05.

Index 0x7nnx Output Data of the Module (0x7000 - 0x7FFF)

This section of the object dictionary defines the output data for the module, focusing on the analog output channels. Each index from 0x7000 onwards corresponds to a specific digital output channel.

Index 0x7000 Digital Output 0

| Index | Name | Data type | Flags | Default |
|-------|----------------|-----------|-------|---------|
| 7000 | DigitalOutput0 | UINT16 | RW | - |

Index 0x7001 Digital Output 1

| Index | Name | Data type | Flags | Default |
|-------|----------------|-----------|-------|---------|
| 7001 | DigitalOutput1 | UINT16 | RW | - |

Index 0x7002 Digital Output 2

| Index | Name | Data type | Flags | Default |
|-------|----------------|-----------|-------|---------|
| 7002 | DigitalOutput2 | UINT16 | RW | - |

Index 0x7003 Digital Output 3

| Index | Name | Data type | Flags | Default |
|-------|----------------|-----------|-------|---------|
| 7003 | DigitalOutput3 | UINT16 | RW | - |

Index 0x7004 Digital Output 4

| Index | Name | Data type | Flags | Default |
|-------|----------------|-----------|-------|---------|
| 7004 | DigitalOutput4 | UINT16 | RW | - |

Index 0x7005 Digital Output 5

| Index | Name | Data type | Flags | Default |
|-------|----------------|-----------|-------|---------|
| 7005 | DigitalOutput5 | UINT16 | RW | - |

Index 0x7006 Digital Output 6

| Index | Name | Data type | Flags | Default |
|-------|----------------|-----------|-------|---------|
| 7006 | DigitalOutput6 | UINT16 | RW | - |

Index 0x7007 Digital Output 7

| Index | Name | Data type | Flags | Default |
|-------|----------------|-----------|-------|---------|
| 7007 | DigitalOutput7 | UINT16 | RW | - |

Warranty

This product is warranted to be in good working order for a period of one year from the date of purchase. Should this product fail to be in good working order at any time during this period, we will, at our option, replace or repair it at no additional charge except as set forth in the following terms. This warranty does not apply to products damaged by misuse, modifications, accident or disaster. Vendor assumes no liability for any damages, lost profits, lost savings or any other incidental or consequential damage resulting from the use, misuse of, originality to use this product. Vendor will not be liable for any claim made by any other related party. Return authorization must be obtained from the vendor before returned merchandise will be accepted. Authorization can be obtained by calling or faxing the vendor and requesting a Return Merchandise Authorization (RMA) number. Returned goods should always be accompanied by a clear problem description.

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