

QEC-M-02 Local 24V Isolated I/O Timing Report, with LT238 & LT233H

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The following summarizes the behavior of the local 24V isolated I/O on QEC-M-02, with a clear mapping to DO (0→1), and comparison to LT238 (DO) vs. LT233H (DO) with LA212 (DI).

1) Purpose

The customer requested high-speed I/O timing characterization with emphasis on the **0→1 (rising-edge)** response.

Current configuration:

- QEC-M-02 uses a **Vortex86EX2** CPU, Master core clock: **533 MHz**, Slave core clock: **400 MHz**
- **DI**: LA212 photocoupler (24V isolated)
- **DO**: LT238 or LT233H Photo MOS-FET relay (24V isolated)

This report compares two DO device options used on the QEC-M-02 local 24V isolated output stage:

- **LT238 (DO)**

Transmission	Turn-On Time	T _{on}		0.25	0.35	ms	I _F =5mA, I _L =100mA,
	Turn-Off Time	T _{off}		0.02	0.05	ms	

- **LT233H (DO)**

Transmission	Turn-On Time	T _{on}		0.15	0.5	ms	I _F =5mA, I _L =100mA,
	Turn-Off Time	T _{off}		0.05	0.5	ms	

The **DI stage is kept identical (LA212)** to ensure the measured differences reflect DO device behavior, especially during **0→1** transitions.

- **LA212 (DI)**

	Rise Time	t _r		6		μs	V _{ce} =5V, I _c =2mA, R _L =100Ω
	Fall Time	t _f		6		μs	

Architecture:

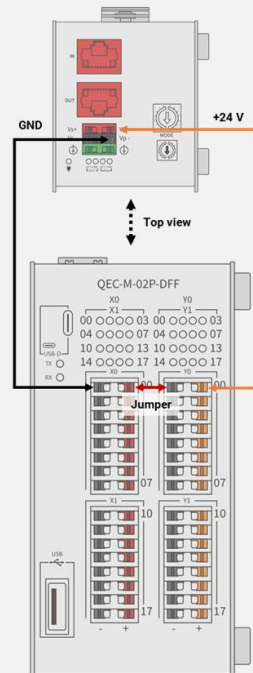
A loopback wiring method was used to validate the local 24V isolated I/O path under the same DI condition:

- Field power rails: +24V and +24V GND (0V)
- A short jumper (“loopback wire”) connects: QEC DO (Y00 / DQ) → QEC DI (X00 / DI)
- Initial condition: In `setup()`, DO is forced to LOW and held for stabilization before starting repetitive switching.

This makes the signal path:

EX2 GPIO OUT → LT238 or LT233H (DO stage) → external loopback → LA212 (DI stage) → EX2 GPIO IN

Diagram



2) Measurement (Rising-Edge 0→1)

The firmware repeatedly generates a 0→1 transition on the DO channel and confirms its arrival at the DI channel by polling.

This test is a **local 24V isolated I/O loopback** measurement (**DO→DI path**) with a known initial state.

Measurement flow (DO→DI, 0→1)

- Use EX2 `rdtsc` / `timer_GetClocks64()` to measure latency. At **533 MHz**, **1 tick ≈ 1.875 ns**.
 1. Force initial state: **Y00 = LOW** in `setup()` and wait for stabilization.
 2. Disable interrupts to reduce software jitter (`io_DisableINT()`).
 3. Timestamp **t0**.
 4. Set **Y00 = HIGH** (rising-edge 0→1).
 5. Busy-wait until **X00 == 1**.
 6. Timestamp **t1**.
 7. Compute **0→1 delay = t1 - t0**.
 8. Repeat and record min/max.

The measured value represents the local loopback propagation delay for the **0→1 rising edge**, including:

1. DO turn-on behavior (**dominant for 0→1**)
2. DI threshold crossing (LA212)
3. software polling detection granularity (minimized by tight loop + interrupts disabled)

Oscilloscope cross-check: A **Tektronix TDS2012C (100 MHz, 2 GS/s)** was used to observe the rising-edge waveform shape for cross-validation.

3) Results Summary (0→1 Focus)

Under room temperature (~25 °C) and standard 24V test conditions, the measured on-board 24V DO/DI timing is:

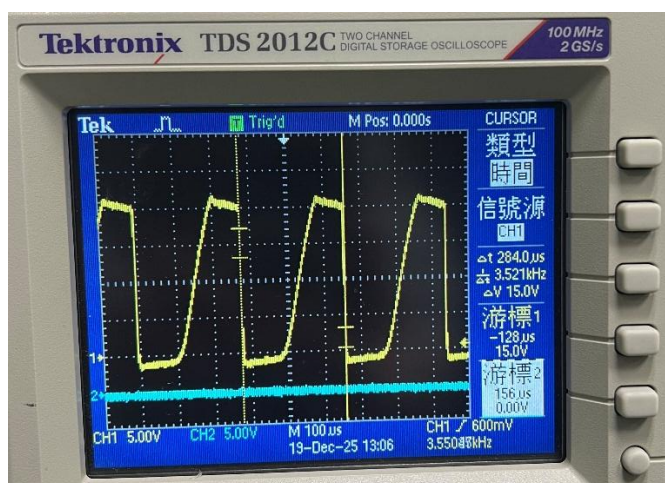
Measured propagation delay (μs)

Case	DO Device	DI Device	0→1 (ret01) Min	0→1 (ret01) Max	1→0 (ret10) Min	1→0 (ret10) Max
A	LT238	LA212	206.6	244.5	97.9	102.1
B	LT233H	LA212	67.3	80.7	90.9	94.2

Key findings (Rising-edge 0→1)

- **Dominant difference is the rising edge (0→1).**
LT233H reduces the 0→1 delay by:
 - **Min improvement:** $206.6 - 67.3 = 139.3 \mu\text{s}$
 - **Max improvement:** $244.5 - 80.7 = 163.8 \mu\text{s}$
- **Jitter window (Max-Min) is also improved on 0→1.**
 - LT238: $244.5 - 206.6 = 37.9 \mu\text{s}$
 - LT233H: $80.7 - 67.3 = 13.4 \mu\text{s}$
- **Falling edge (1→0) is similar for both cases** (roughly ~91–102 μs range) and is not the primary differentiator in this comparison.

A (LT238): Oscilloscope and firmware screenshot showing the 0→1 loopback delay range (**206.6–244.5 μs**) with LA212 DI fixed.



```
RDISK, 6-16-2011.      2-MB Memory.
Drive Z: assigned.
FTDI COM3 port init OK. IRQ = 3
CTS=HIGH
CTS=LOW
Start to write data into flash ..... Done
01_min=206.6 01_max=244.5 10_min=97.9 10_max=102.1
```

The image shows a Tektronix TDS 2012C oscilloscope. The top of the device has a label that reads "Tektronix TDS 2012C TWO CHANNEL DIGITAL STORAGE OSCILLOSCOPE". To the right of this label, there is a red banner with the text "100 MHz" and "2 GS/s". The oscilloscope screen displays a square wave signal. The screen is divided into several sections:

- Top Left:** The Tek logo and a small icon of a square wave.
- Top Center:** "Trig'd" with a green square icon and "M Pos: 0.000s".
- Top Right:** "CURSOR" and a list of measurement parameters:
 - 類型 (Type): 時間 (Time)
 - 信號源 (Signal Source): CH1
 - Δt : 174.0 μ s
 - Δf : 5.747 kHz
 - ΔV : 9.20 V
- Bottom Left:** "CH1 5.00V", "CH2 5.00V", "M 50.0 μ s", and "19-Dec-25 13:14".
- Bottom Right:** "CH1 15.4V" and "5.71434 kHz".

The square wave signal is displayed in yellow on a black background with a white grid. The signal has a period of approximately 10 divisions and a peak-to-peak voltage of approximately 18.4 V. The horizontal scale is 50.0 μ s/div, and the vertical scale is 15.4 V/div. The screen also displays two cursors: "游標 1" (Cursor 1) and "游標 2" (Cursor 2). The signal is labeled "CH1" and "CH2".

```
RDISK, 6-16-2011.      2-MB Memory.  
Drive 2: assigned.  
FTDI COM3 port init OK. IRQ = 3  
CTS=HIGH  
CTS=LOW  
Start to write data into flash ..... Done  
01_min=67.3 01_max=80.7 | 10_min=90.9 10_max=94.2
```

Based on the local 24V isolated I/O loopback measurement with:

- Therefore, LT233H is recommended** for applications requiring a faster 0→1 response on QEC-M-02 local 24V isolated outputs, while maintaining the same DI device (LA212).